

CAESES® – Current developments and perspectives

Stefan Harries

Intelligent Industrial Design Technology Seminar &
Tianfu Hipoint Software Product Users Conference

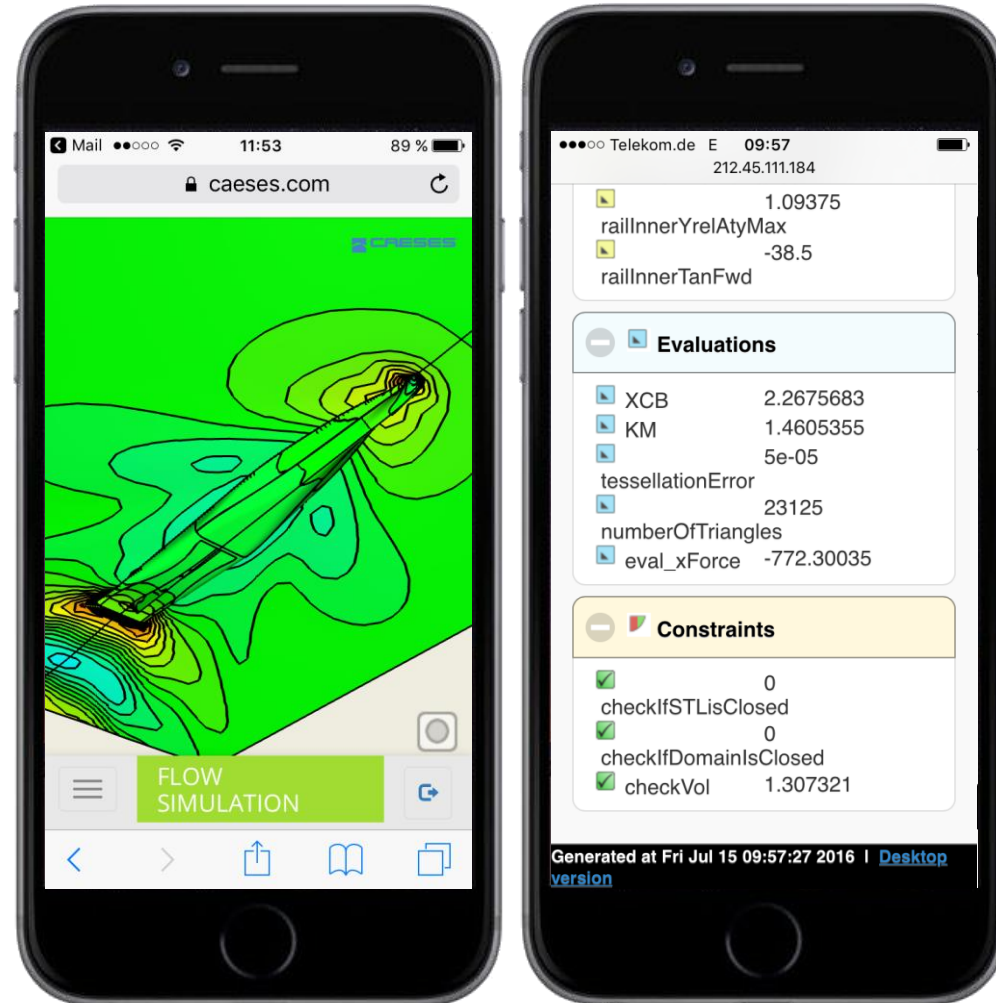
Ningbo, October 27, 2017



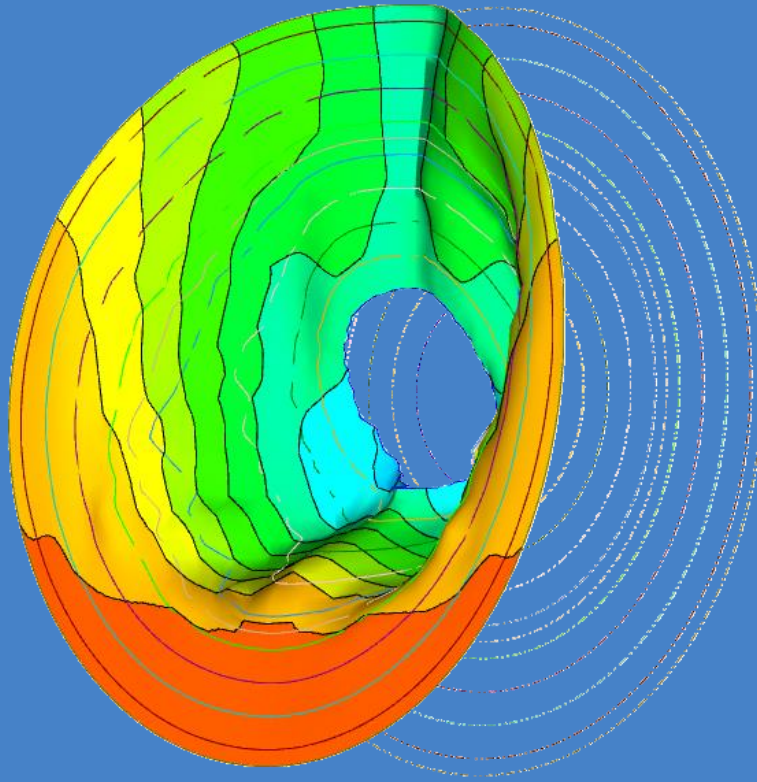
FRIENDSHIP SYSTEMS

Content

- State-of-the-art
- Recent and current R&D
- CAESES 5.0
- Appification and WebApps
- Sneak preview: Interactive shape variation

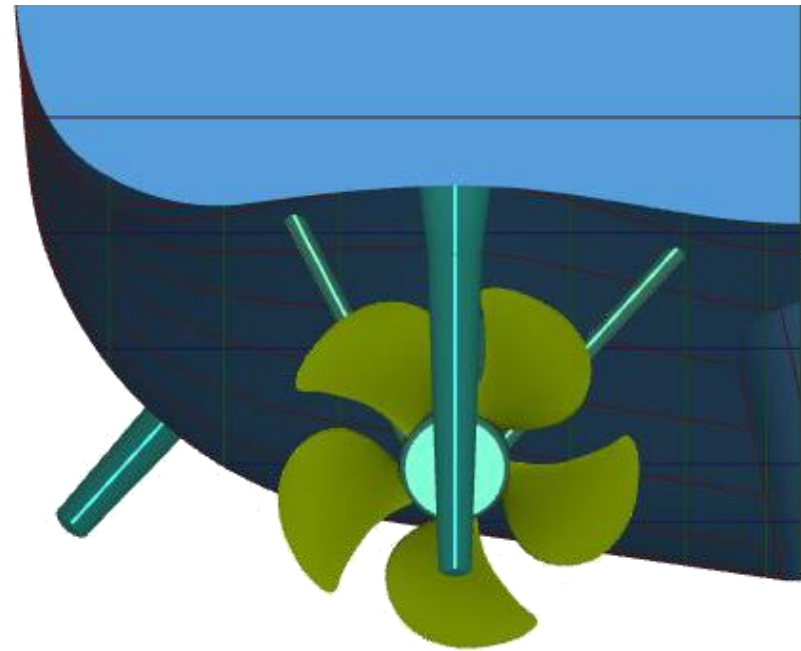


State-of-the-art



State-of-the-art: thyssenkrupp Marine Systems

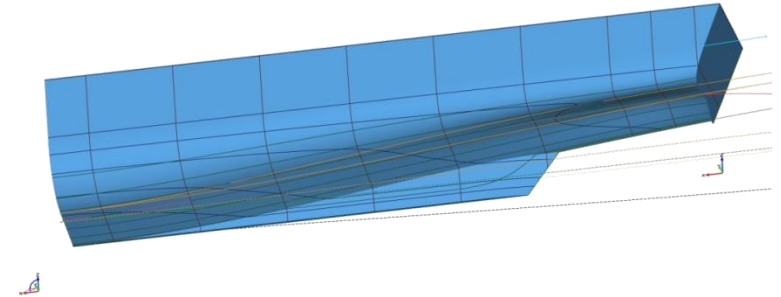
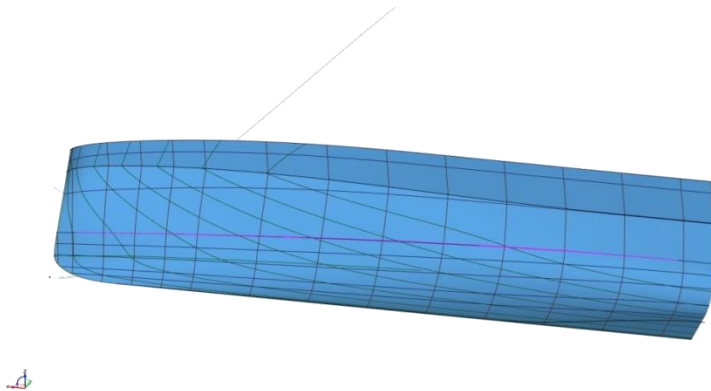
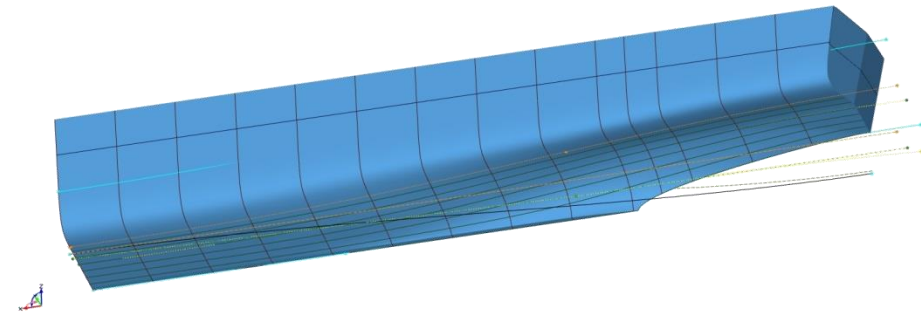
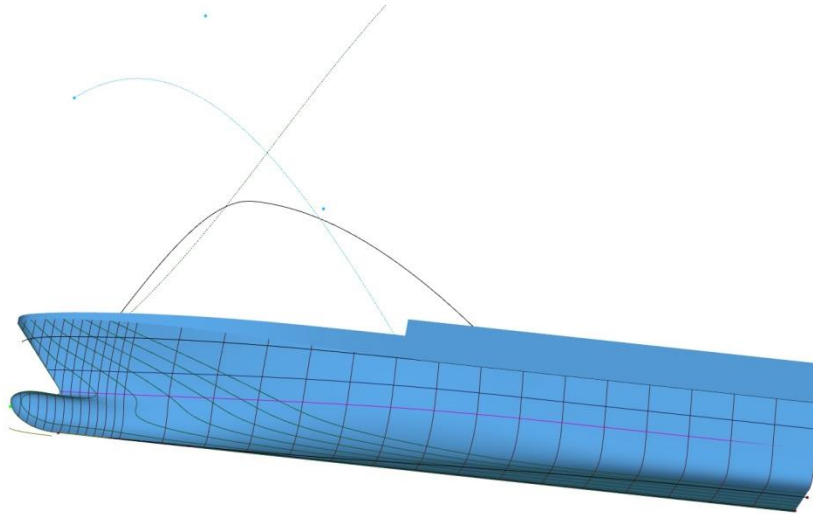
- Virtual prototyping of fully-appended vessels
 - Several parametric models for fore- and aftbody
 - Parametric models for appendages
 - Coupling of CAESES with potential flow code and ANSYS CFX
- Process chain for fast and reliable studies
 - What-ifs
 - Quick checks (e.g. increased displacement)
 - Trade-offs
 - Formal optimization (e.g. interceptor)



State-of-the-art: Standard models for combination



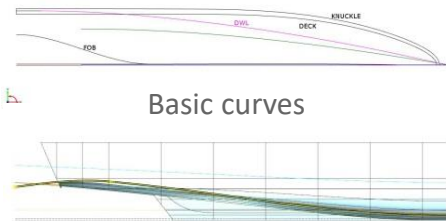
thyssenkrupp



State-of-the-art: thyssenkrupp Marine Systems

1

Parametric modeling



2

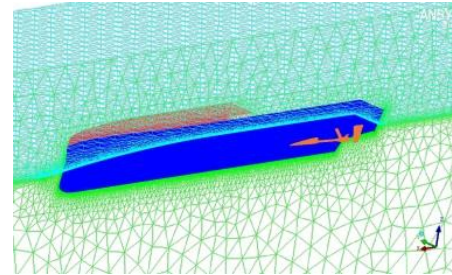
Optimization
(potential flow)

Design Variables					
Design Variable	Lower	Value	Upper	Active	
1 v_SatAPPrvBase	-1.10	120	130	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
2 v_SatAPPrvBase	-0.1	0.1278	0.15	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
3 v_SatAPPrvBase	-4	4	5.2	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
4 v_SatAPPrvBase	-0.97	0.982	0.993	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
5 v_SatAPPrvBase	-34	34	39	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
6 v_SatAPPrvBase	-2.5	0.675	0.7	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
7 v_SatAPPrvBase	-0.01	-0.01	0.006	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
8 v_SatAPPrvBase	-0.0005	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
9 v_SatAPPrvBase	-0.01	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
10 v_SatAPPrvBase	-0.84	0.9240187	0.96	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
11 v_SatAPPrvBase	-0.06	-0.023	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
12 v_SatAPPrvBase	0	0.1	0.2	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
13 v_SatAPPrvBase	0	0	0.1	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
14 dv_tgElevation	-1.8	1.9	2	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
15				<input type="checkbox"/>	<input type="checkbox"/>

Free variables

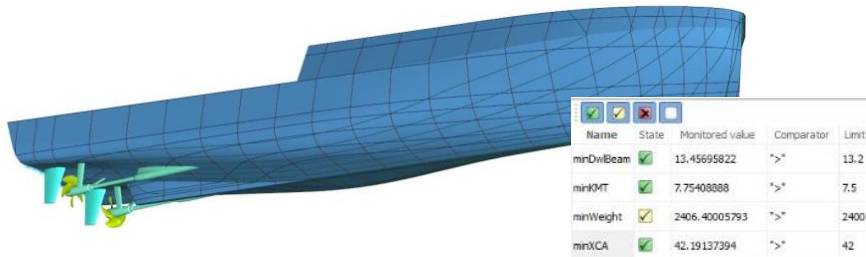
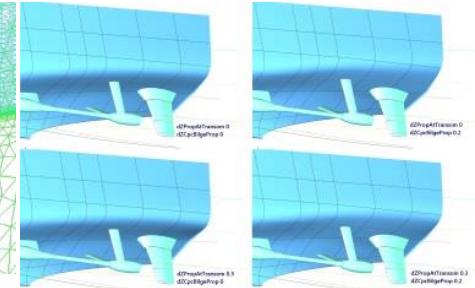
3

RANSE simulations



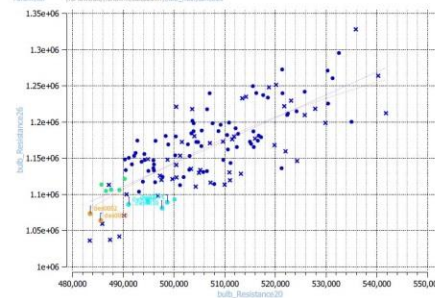
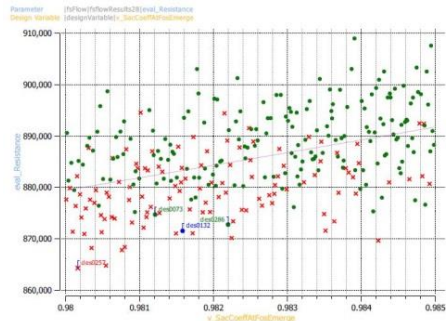
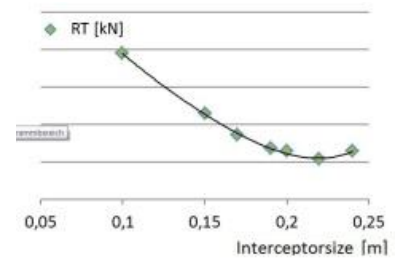
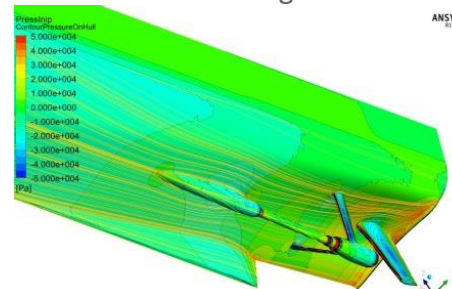
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Optimization

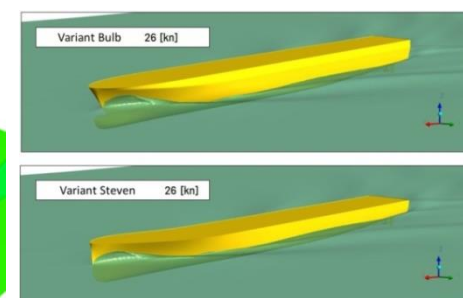
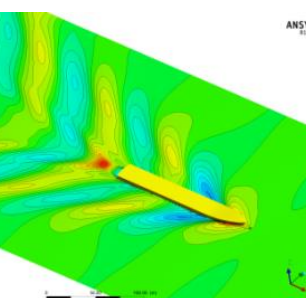


Name	State	Monitored value	Comparator	Limit
minDvlBeam	<input checked="" type="checkbox"/>	13.45695822	">"	13.2
minKMT	<input checked="" type="checkbox"/>	7.75408888	">"	7.5
minWeight	<input checked="" type="checkbox"/>	2406.40005793	">"	2400
minXCA	<input checked="" type="checkbox"/>	42.19137394	">"	42

Constraints

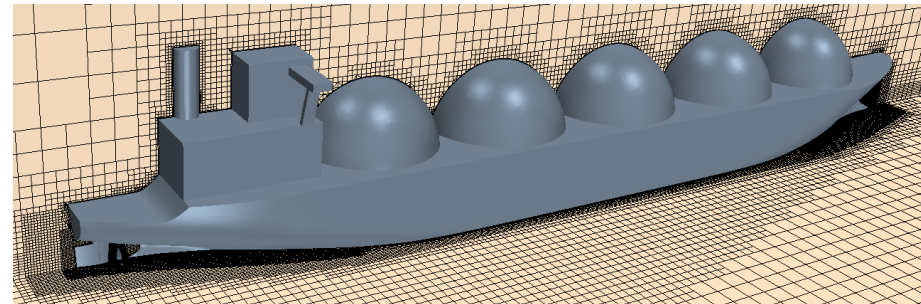
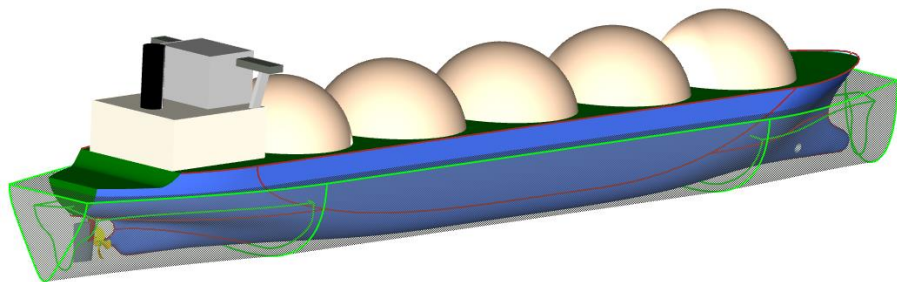
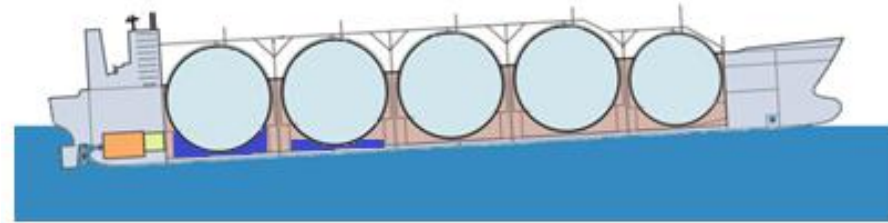
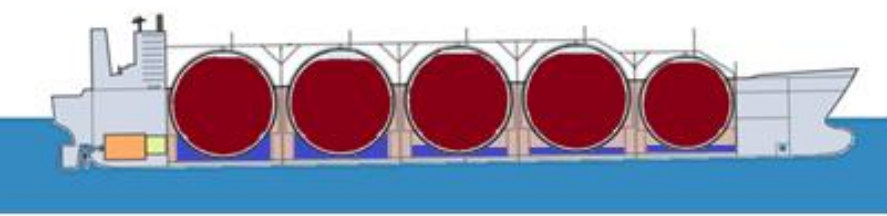


ANSYS



State-of-the-art: University of Strathclyde

- Concept studies
- Pre- and post-processing of CFD for extreme conditions

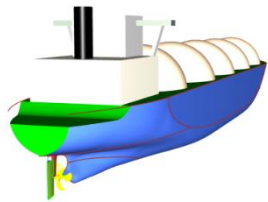


Support grid generation

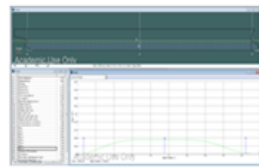
Auxiliary geometry for refinements and better quality



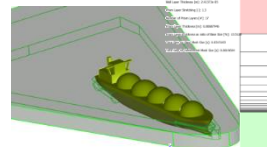
State-of-the-art: Streamlined process



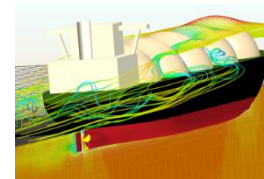
CAESES



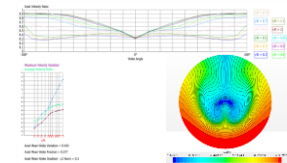
MAXSURF Stability



CAESES



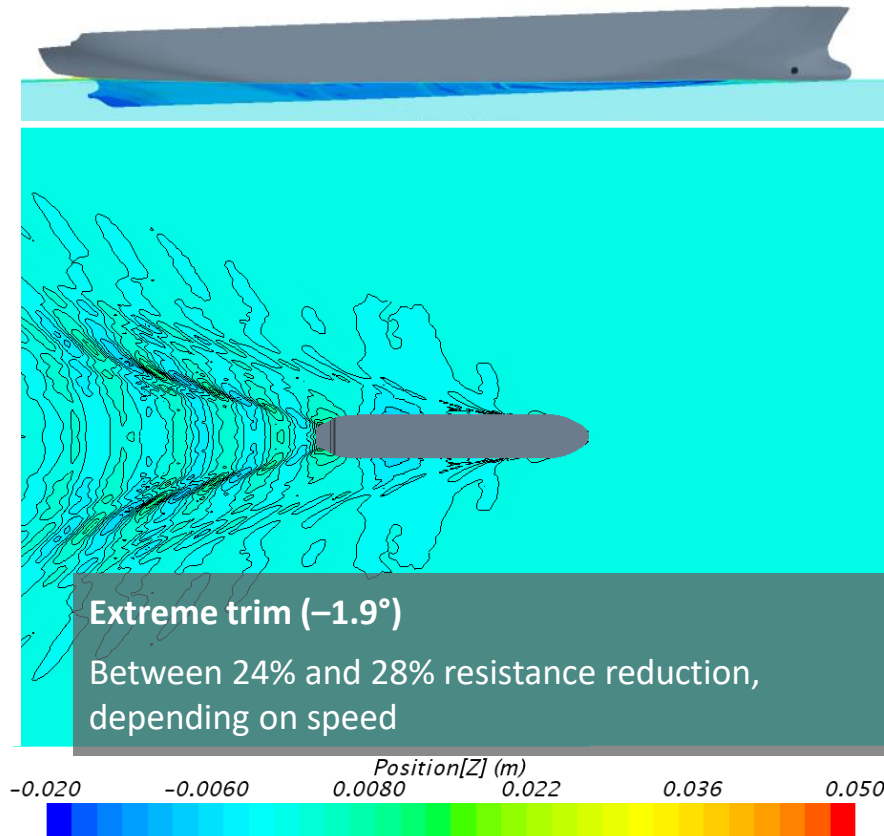
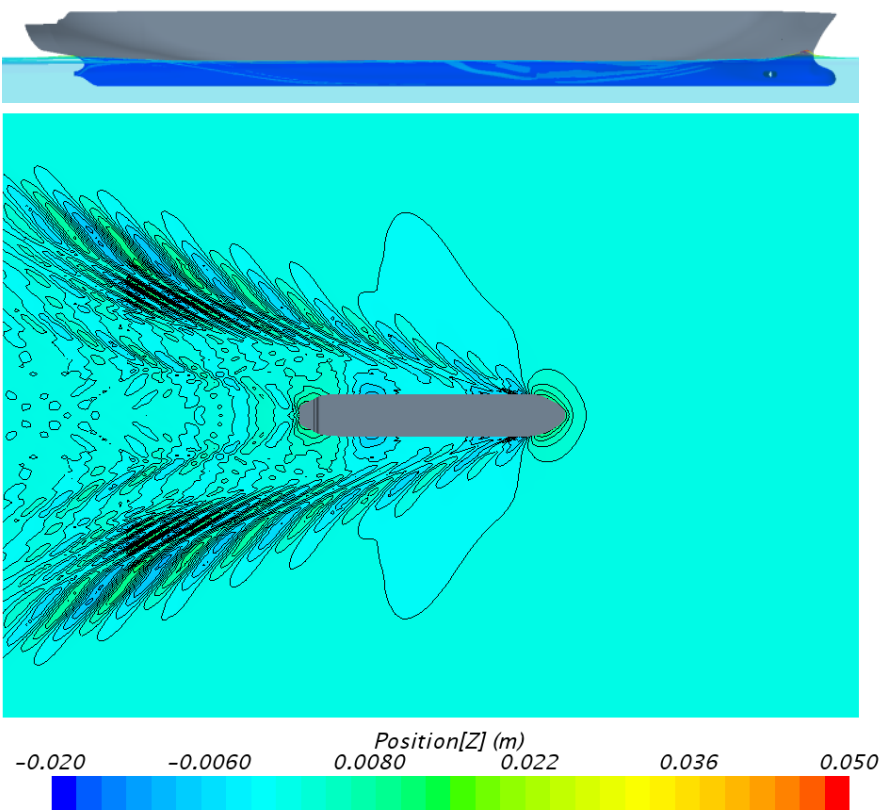
STAR-CCM+



CAESES



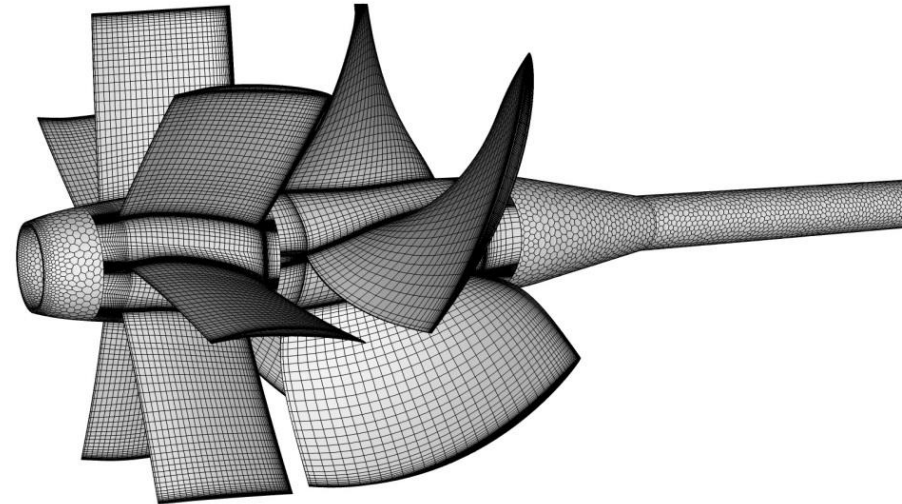
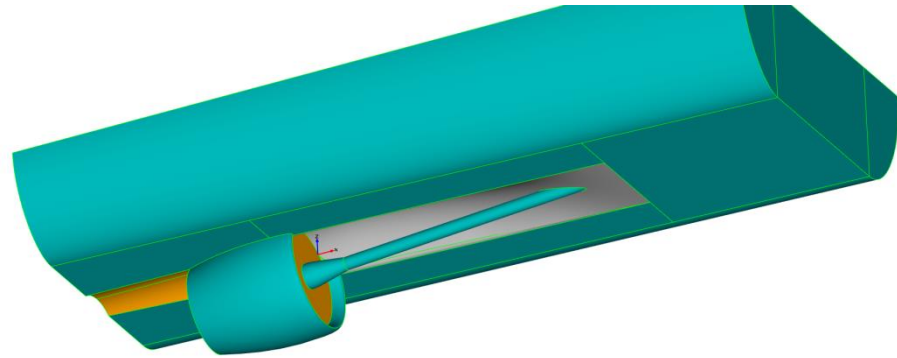
State-of-the-art: Study for extreme conditions



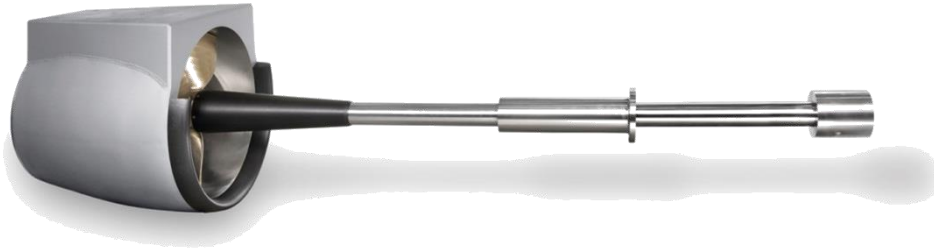
State-of-the-art: Voith

- Advanced parametric modeling of ship hulls and propulsion systems
- Auxiliary geometry to support grid generation

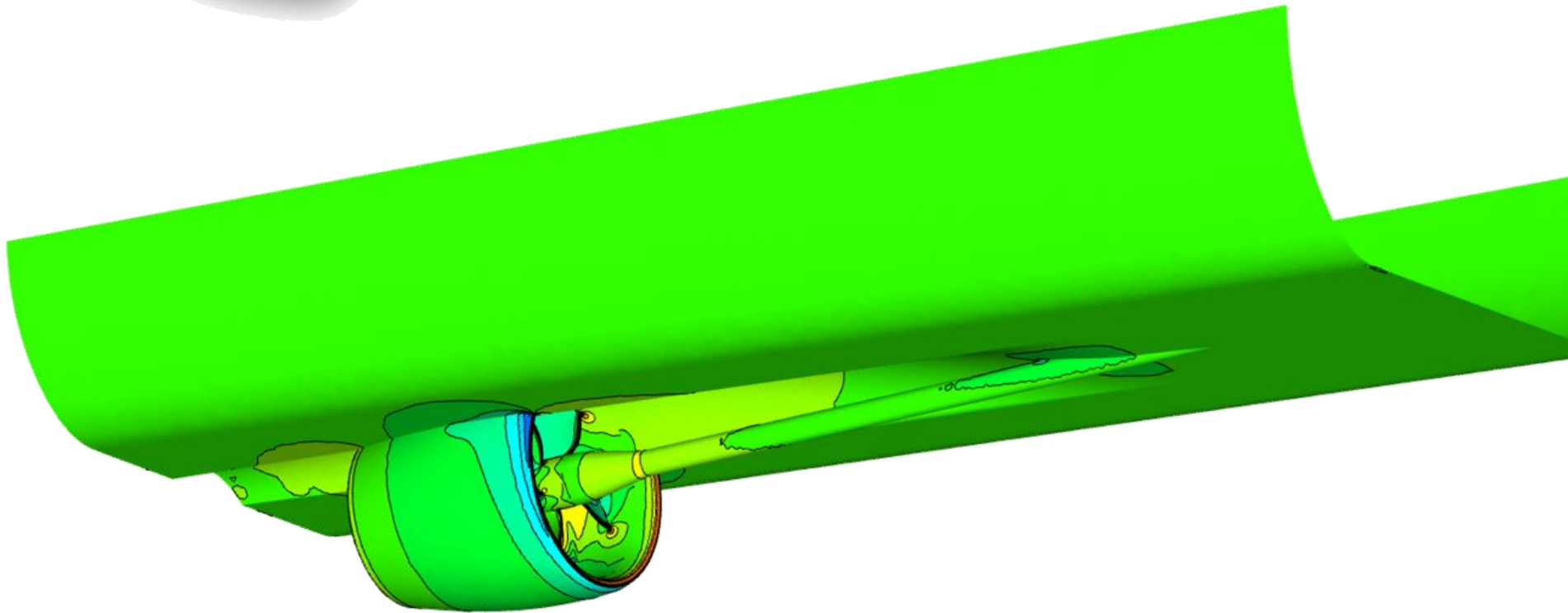
VOITH



State-of-the-art: Voith Linear Jet (VLJ)

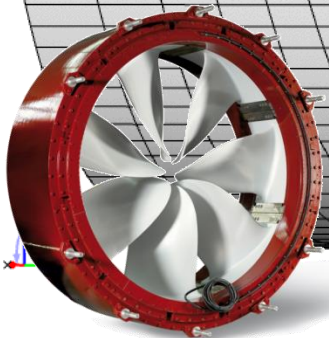


VOITH

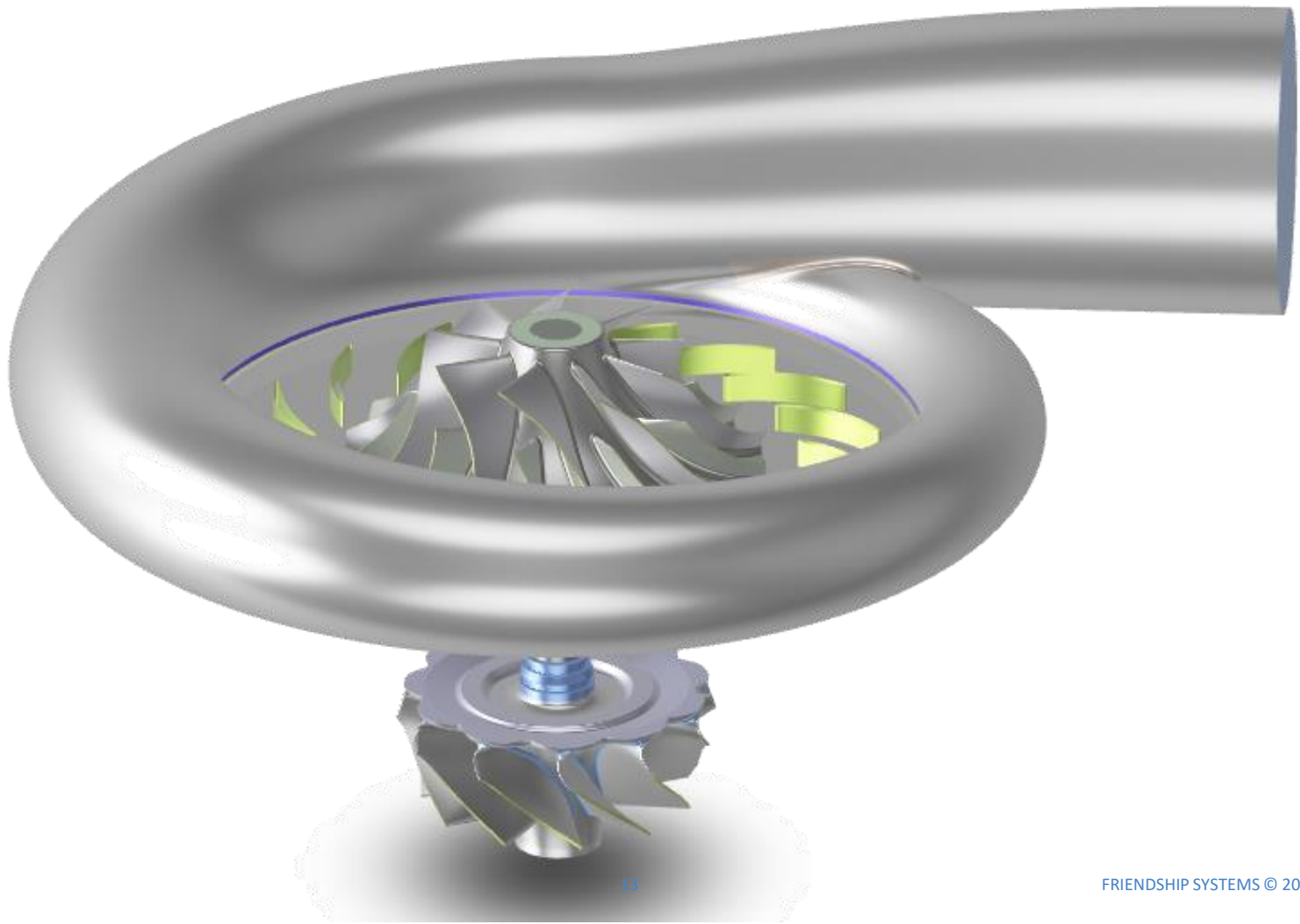


State-of-the-art: Voith Inline Thruster (VIT)

VOITH



Recent and current R&D



Recent and current R&D (highlights)

- PerSee
 - Hydrodynamic design of ships in sea-states
- No-Welle and FormPro
 - Parametric adjoint optimization
- HYKOPS
 - Appification
 - Geometric modeling
- HOLISHIP
 - Holistic design and process integration (platform)
 - Wrapping of functionality (dominos)
- GAMMA-1
 - Parameter reduction (Karhunen-Loève expansion)
 - Ease-of-use and GUI

Acknowledgement

Parts of the work presented here were realized within projects funded by the Federal Ministry of Economics and Technology (BMWi) on the orders of the German Bundestag and PtJ as the conducting agency.

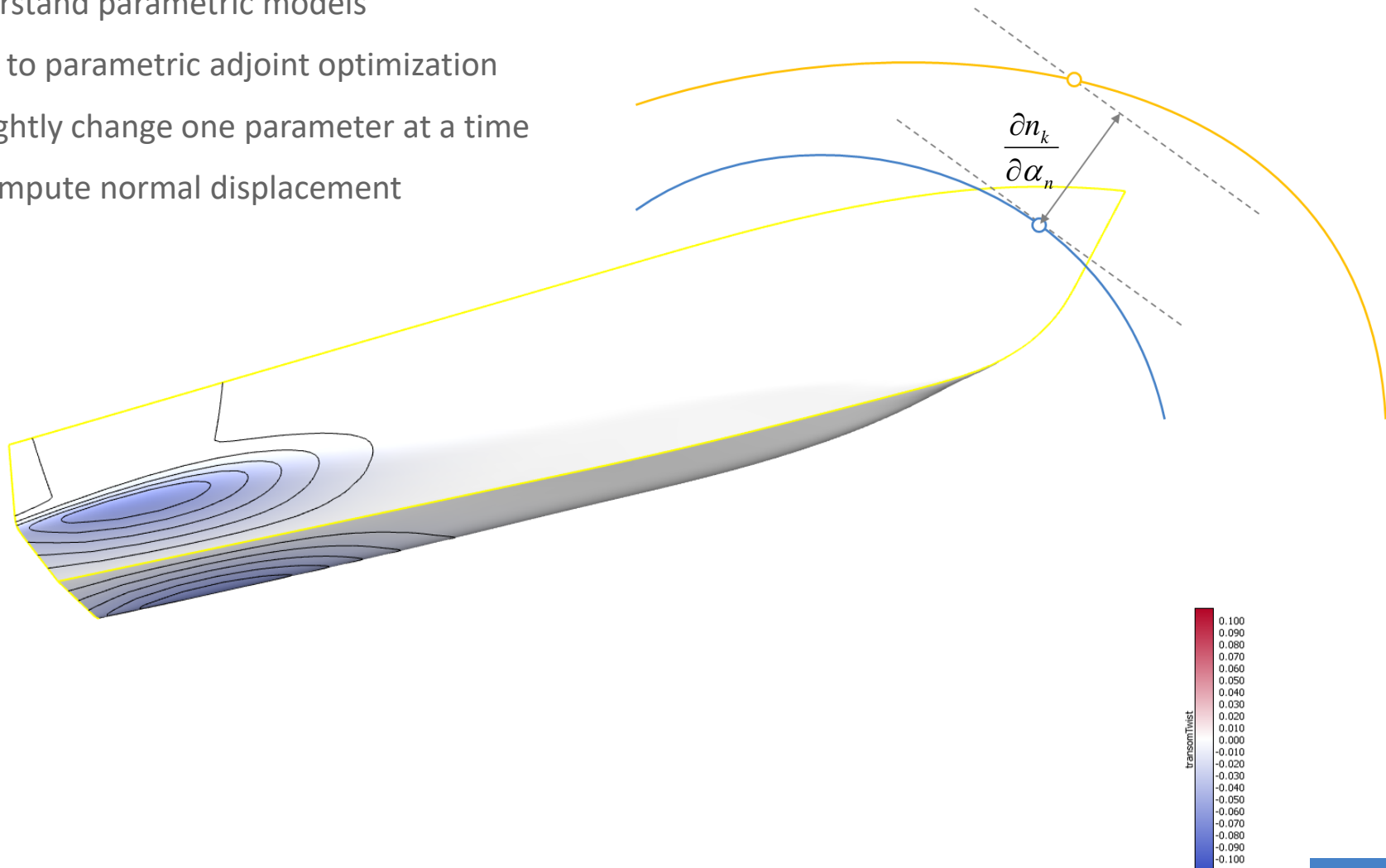
Parts of the work were funded by the European Commission within the HORIZON 2020 Transport Programme.

Funded by the
European Union



Parametric adjoint optimization: Design velocity

- Understand parametric models
- Input to parametric adjoint optimization
 - Slightly change one parameter at a time
 - Compute normal displacement

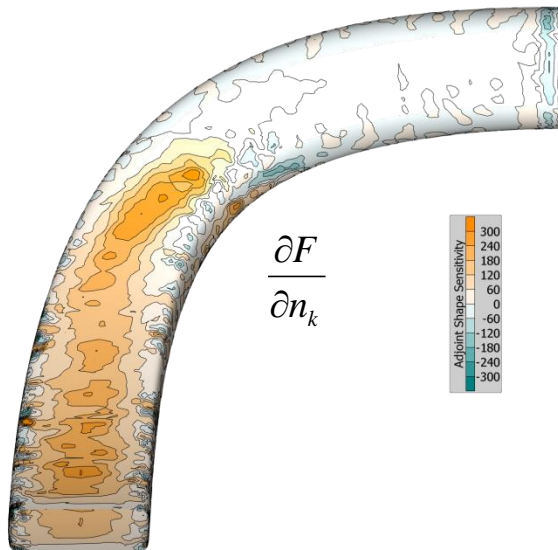


Parametric adjoint optimization

- Results from adjoint CFD computation specify areas of the geometry that have the biggest impact on the objective
- Connecting to information about parameter influence on shape leads to sensitivities for all design parameters

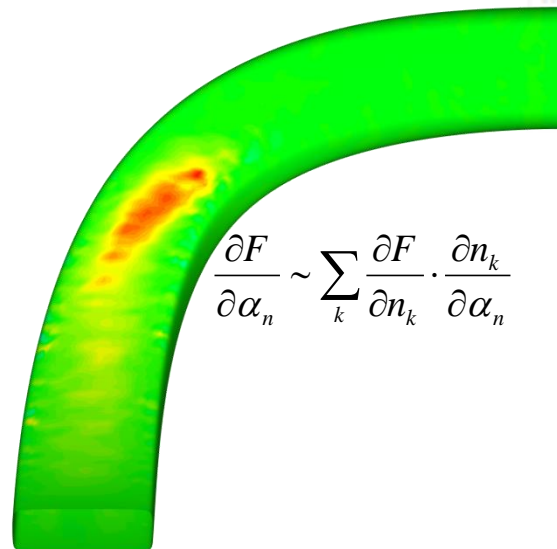
pictures: Sensitivities

	Sensitivity	Variation Delta
width_mid	-41.2465	3.99853
path_midfactorZ	1388.89	0.0208482
path_startTension	562.865	0.0419241
height_startTension	3119.02	0.242158
path_midfactorY	233.01	0.0402543
width_endTension	115.733	0.587913
path_midfactorX	-619.726	0.0205169
width_midPos	-265.585	0.522516
th_endTension	807.685	
height_midPos		

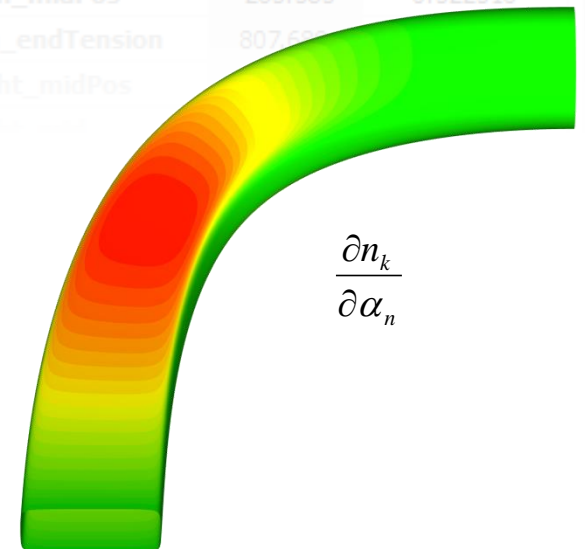


$$\frac{\partial F}{\partial n_k}$$

adjoint shape sensitivity

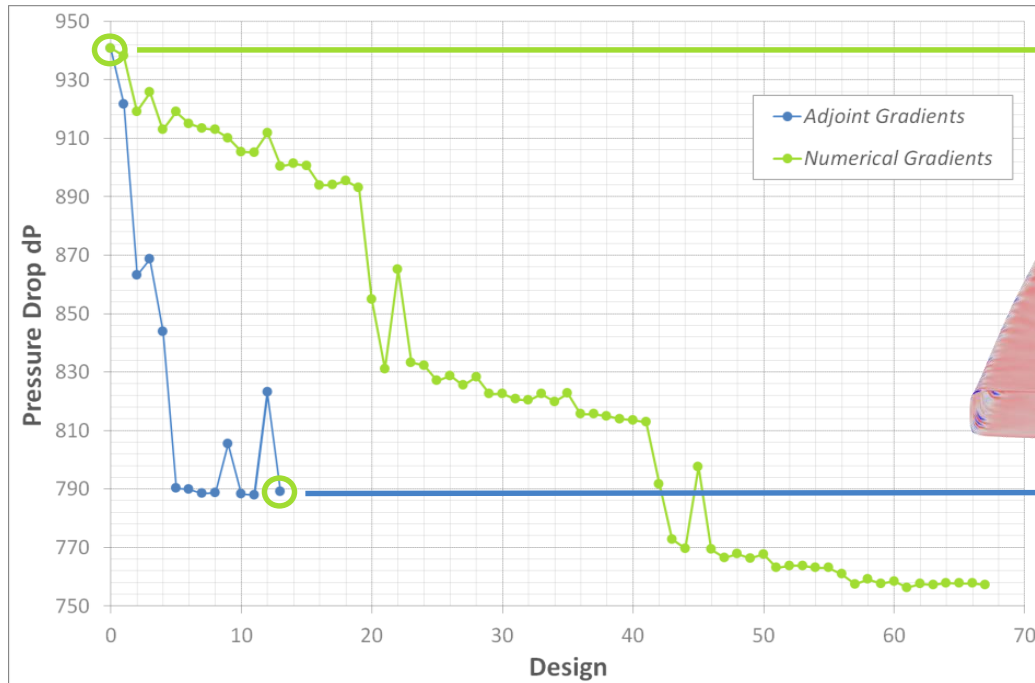


product

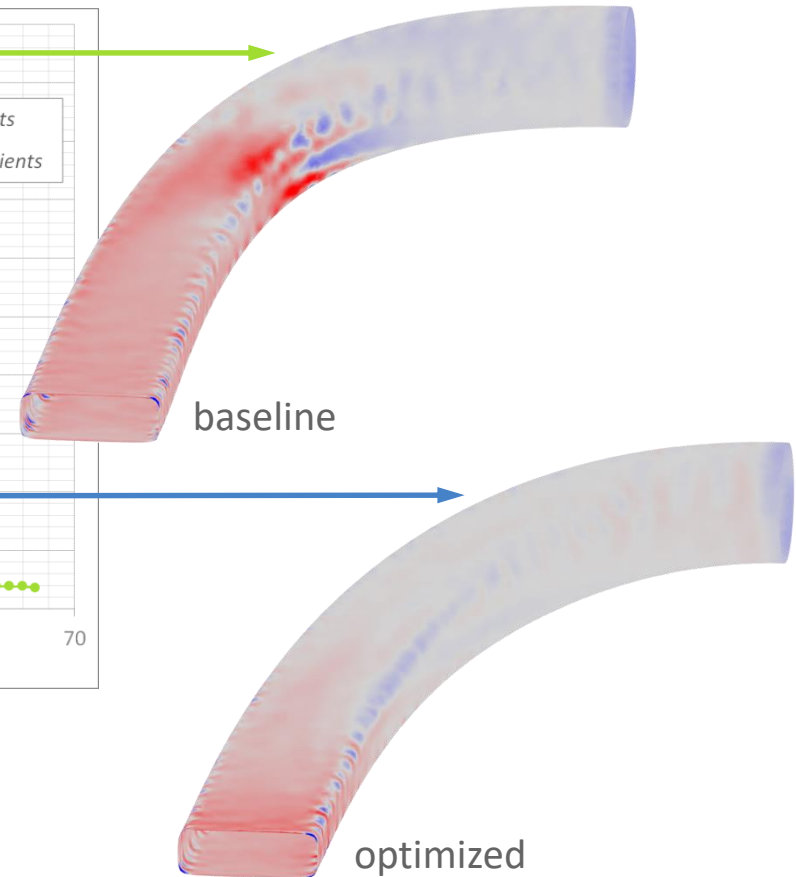


design velocity

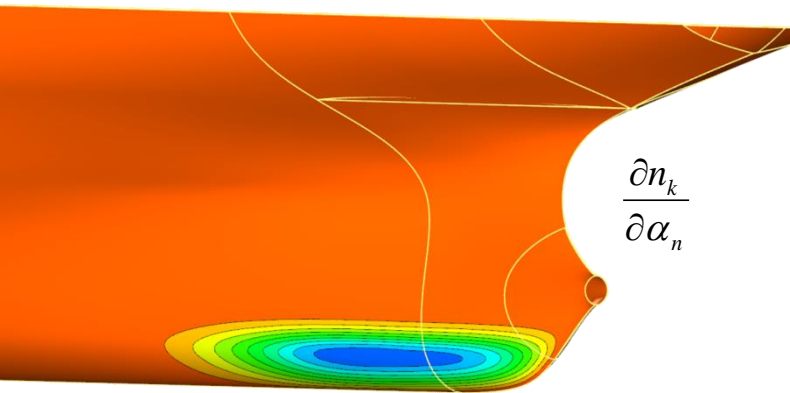
Parametric adjoint optimization



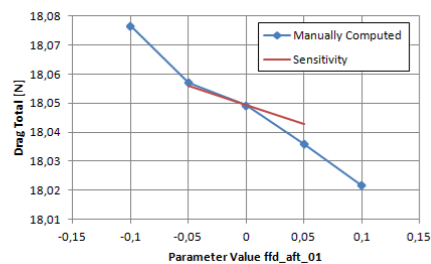
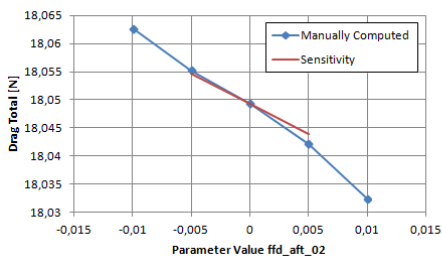
- Using the gradient information from the adjoint CFD leads to a much faster convergence towards a local optimum



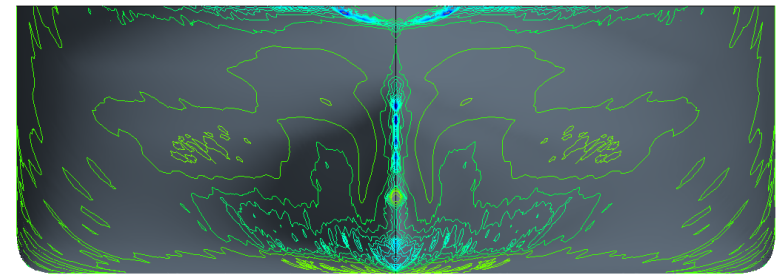
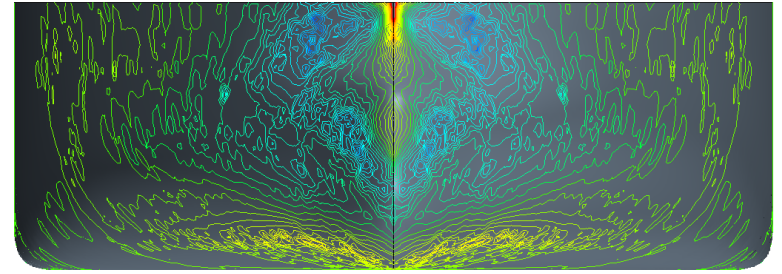
Parametric adjoint optimization



$$\frac{\partial F}{\partial \alpha_n} \sim \sum_k \frac{\partial F}{\partial n_k} \cdot \frac{\partial n_k}{\partial \alpha_n}$$

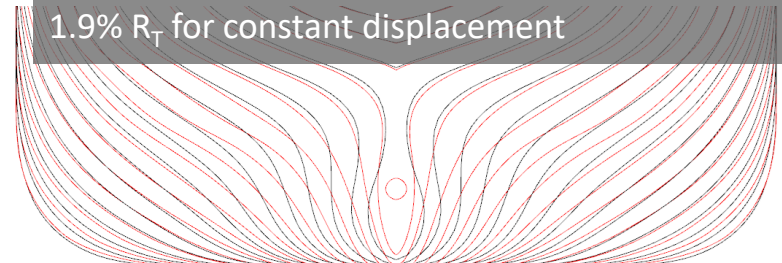


$$\frac{\partial F}{\partial n_k}$$



Improvement of resistance

1.9% R_T for constant displacement



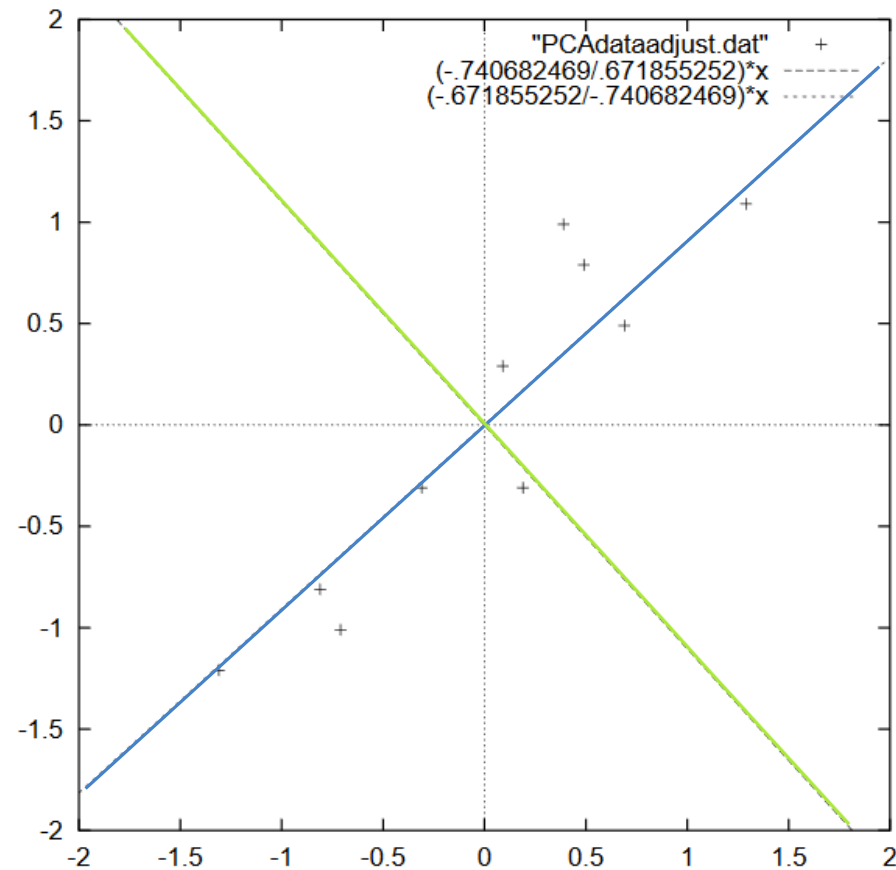
Karhunen-Loève Expansion (KLE)

■ Aims

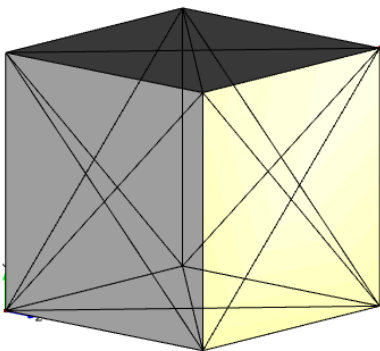
- Check quality of a parametric model
- If needed and possible reduce number of free variables (further)

■ Principle components analysis

- A large number of statistical variable are being replaced by an approximation with a reduced number of linear combinations of orthogonal basis functions
- Decorrelation of data (as far as possible)

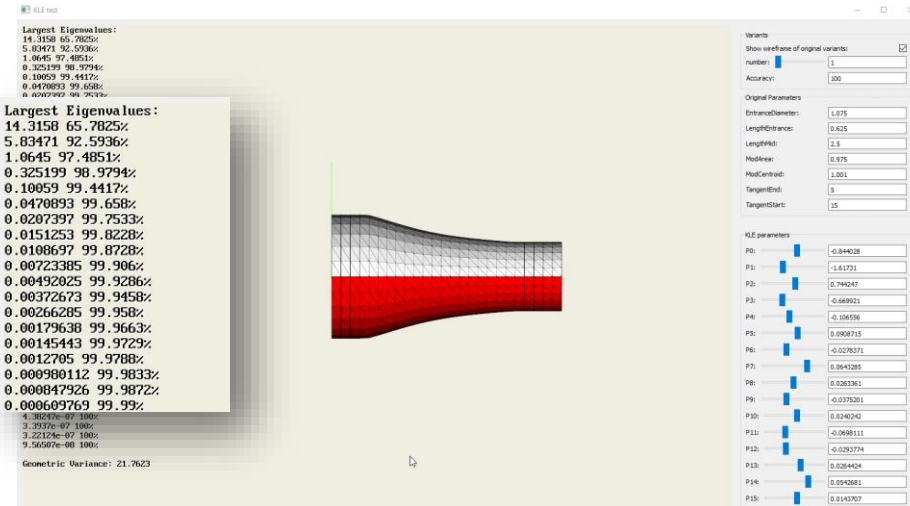
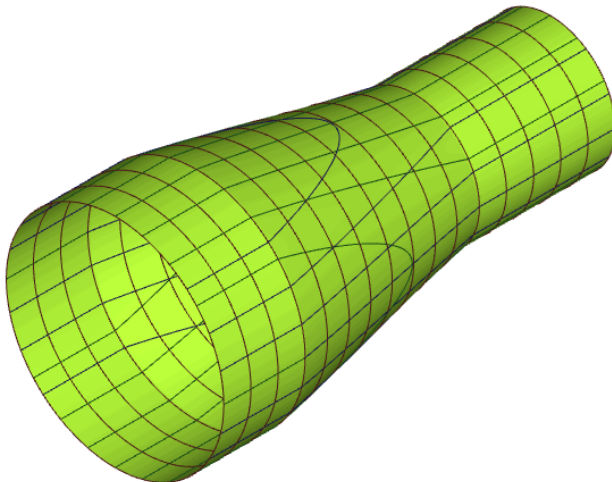


Source: Lindsay I. Smith (2002) A Tutorial on Principal Components Analysis

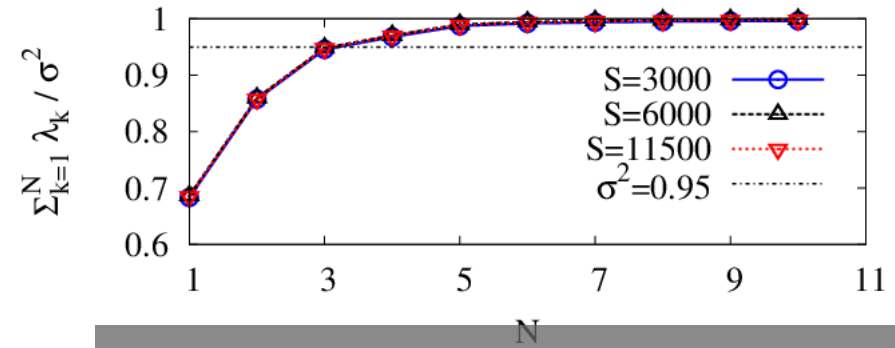
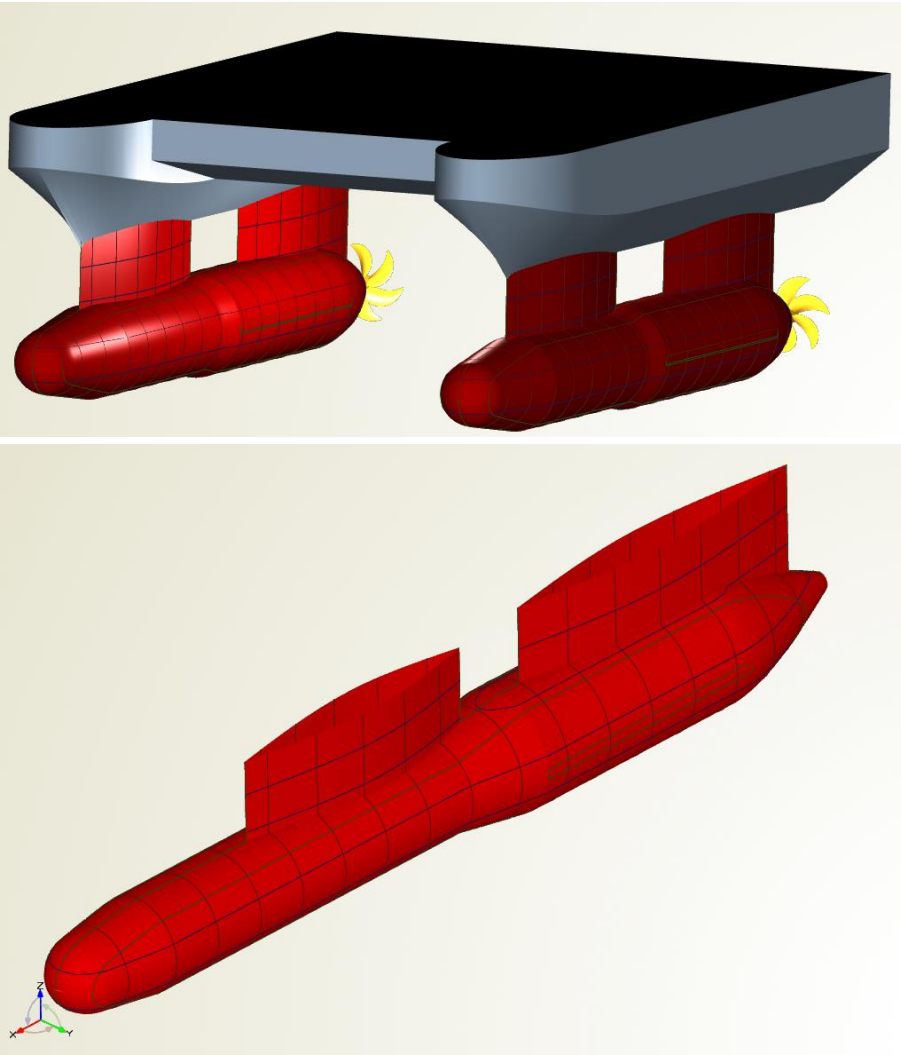


Karhunen-Loève Expansion (KLE)

- Inlet geometry with 7 free variables
- Variability achieved
 - 1. “super parameter” 65,78%
 - 1. + 2. “super parameter” 92,59%
 - 1. + 2. + 3. parameter 97,49%
 - 1. + 2. + 3. + 4. parameter 98,98%
 - 1. + 2. + 3. + 4. + 5. 99,44%



Parameter reduction



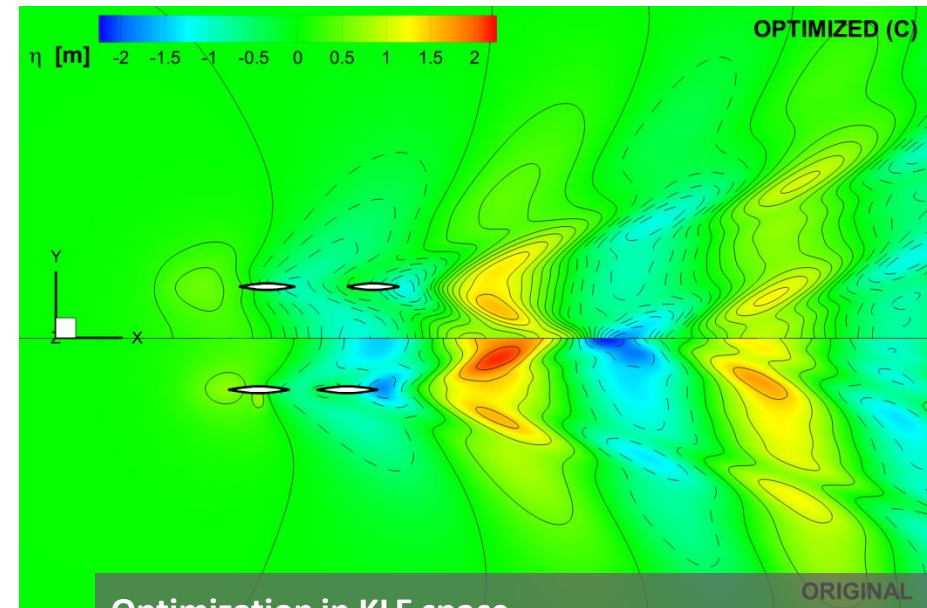
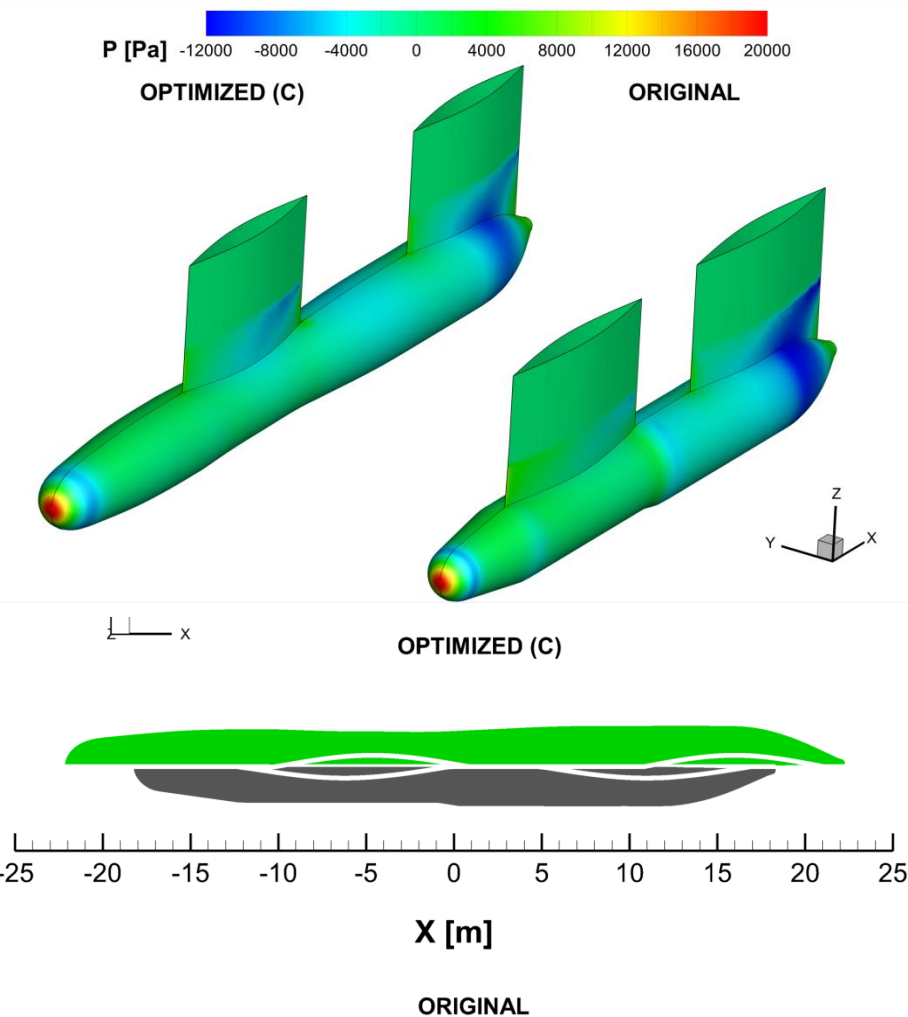
Parameter reduction from 27 to 4

Already 4 modes are sufficient to retain more than 95% of the original variance

From 27 original parameter to 4 KLE variables reduces the dimensionality by more than 85%



Parameter reduction



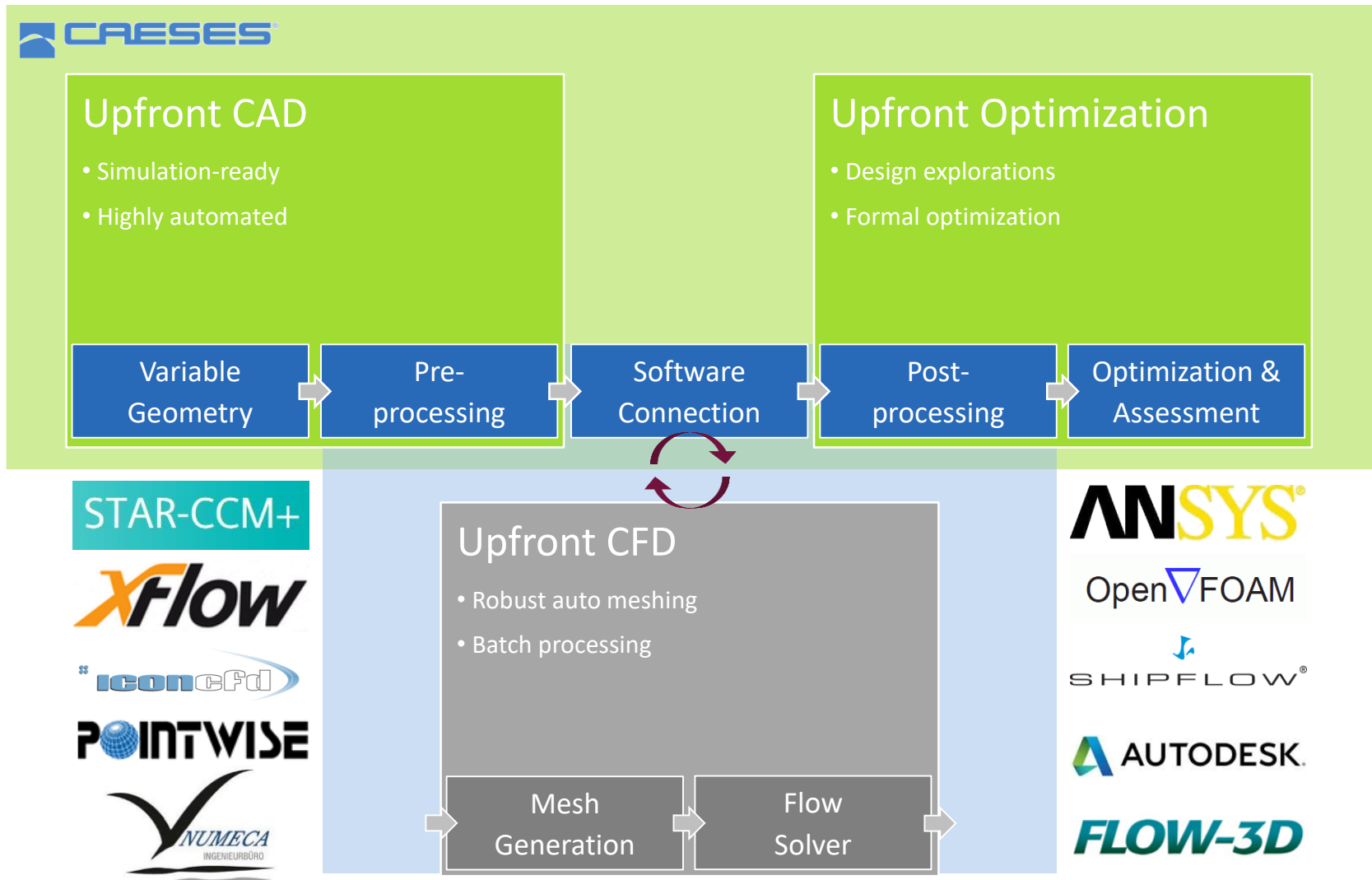
Optimization in KLE space

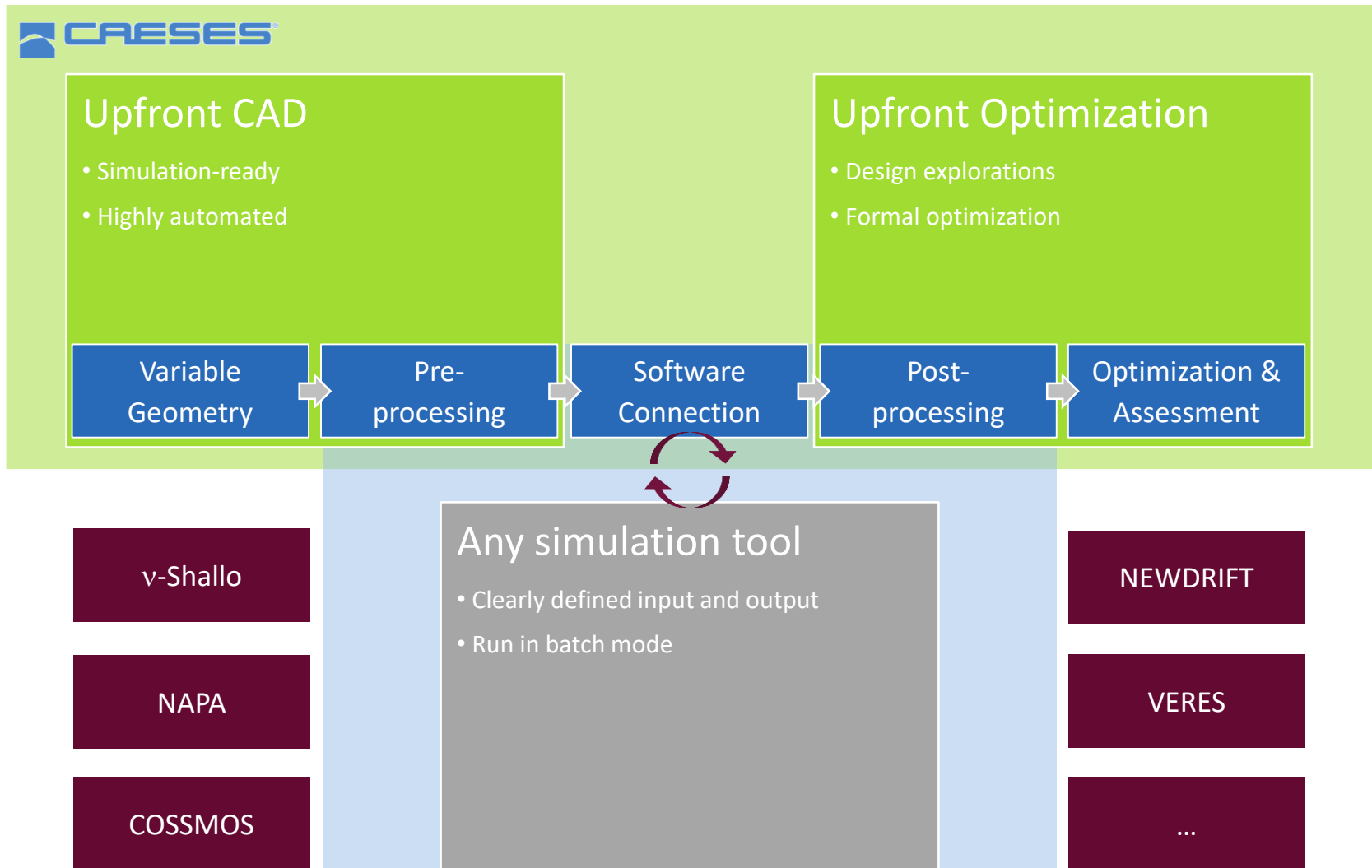
Chosen design shows a reduction of total resistance by about 25% while, at the same time, increasing displacement by around 25%

HOLISHIP

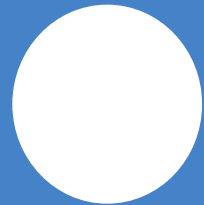
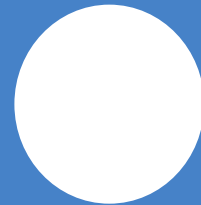
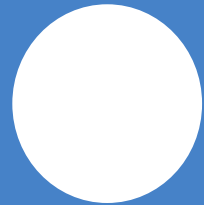
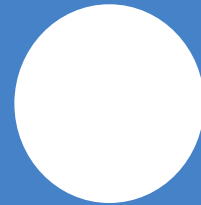


Available integrations

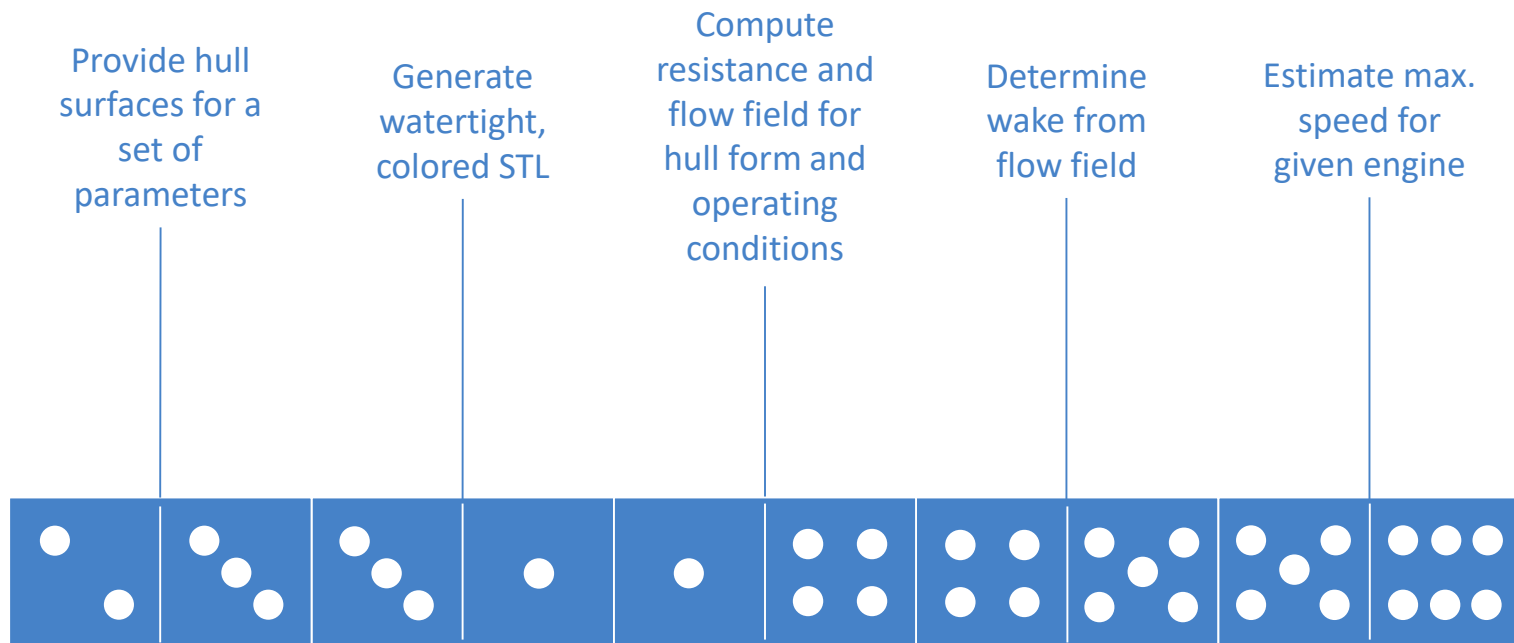




HOLISHIP



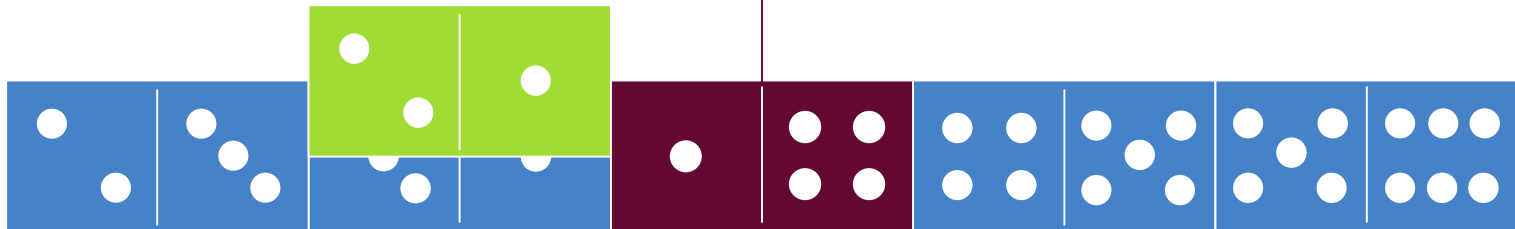
HOLISHIP



HOLISHIP

- Wrap functionality to make it more easily accessible
- Provide wrapped tools that can be flexibly combined within comprehensive projects

Compute
resistance and
flow field for
hull form and
operating
conditions
via a WebApp



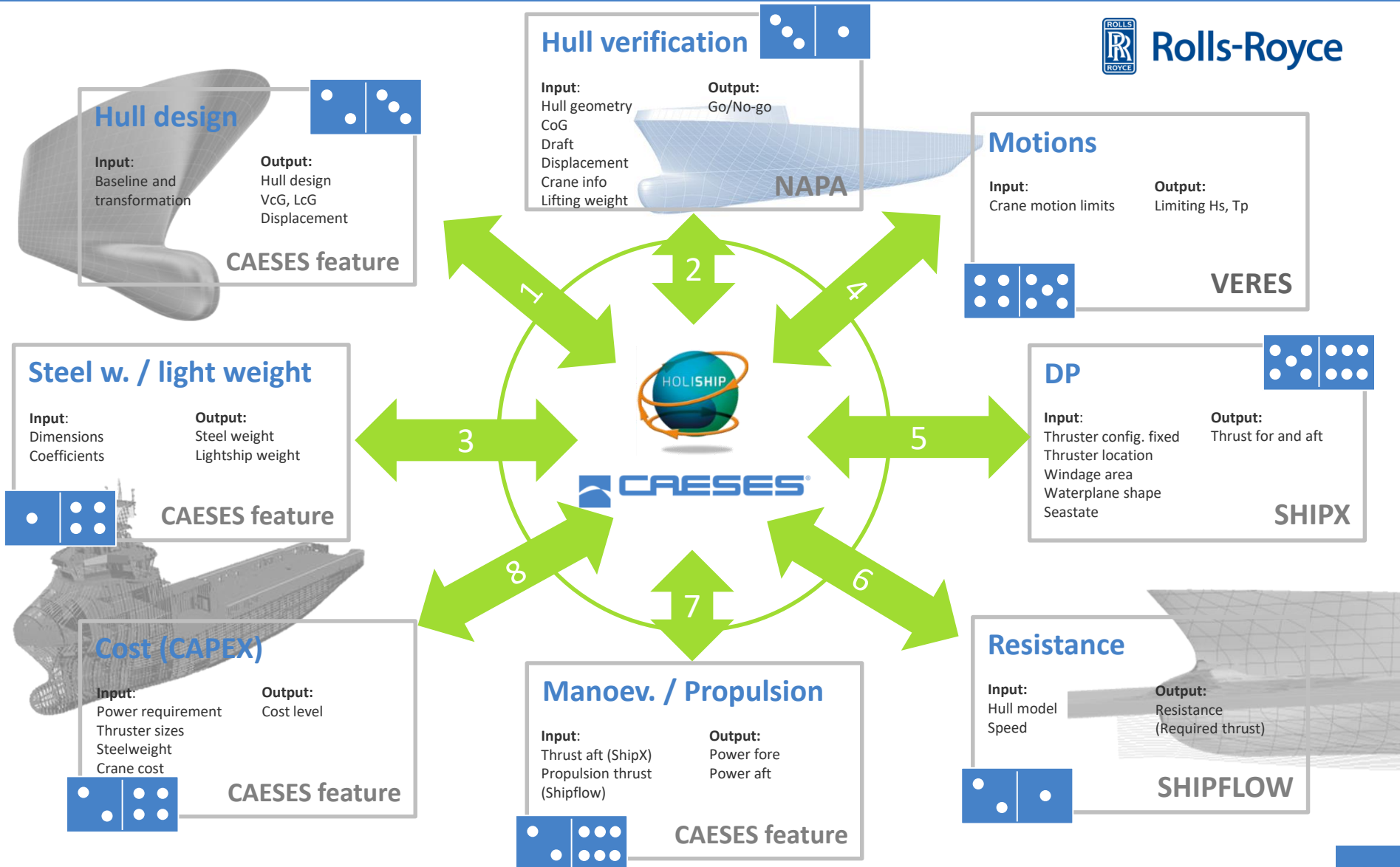
Rolls-Royce



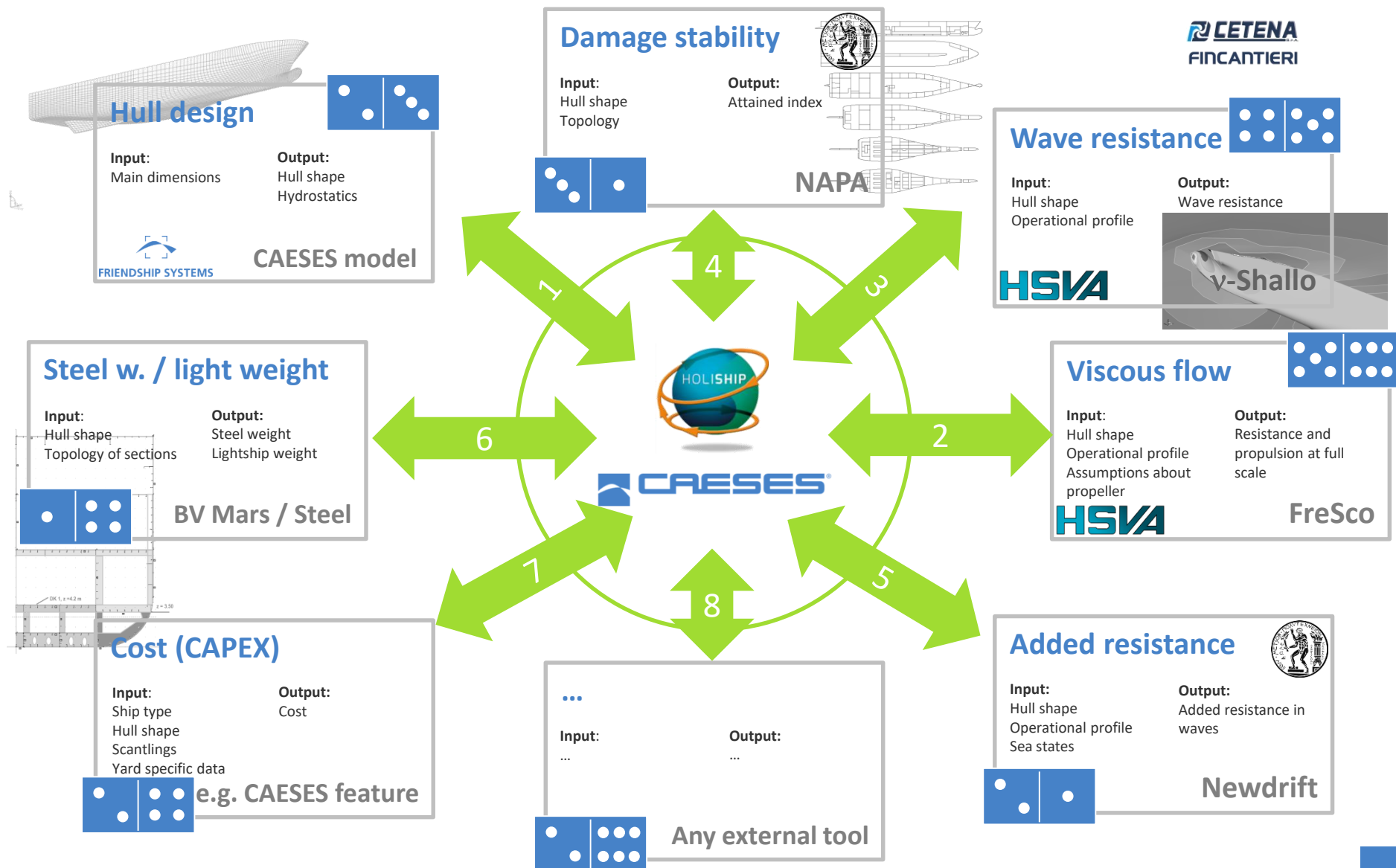
HOLISHIP – Application case Rolls-Royce OSV



Rolls-Royce

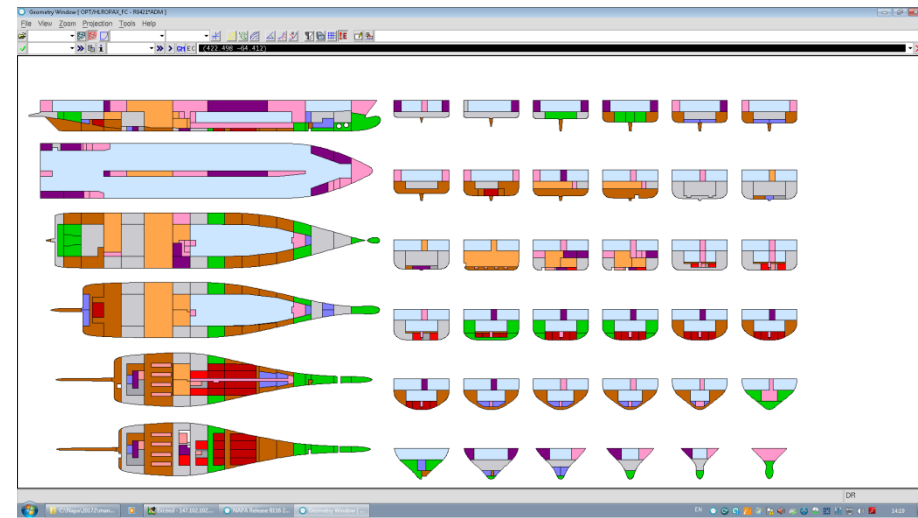


HOLISHIP – Application case FINCANTIERI RoPax



Coupling of CAESES and NAPA

- Hull forms are created in CAESES and surfaces are transferred to NAPA via an IGES file
- A detailed watertight subdivision is created using a series of NAPA macros
- The Attained subdivision index is calculated according to SOLAS 2009 Reg.7
- The above procedure is repeated for a large number of variants via a Sobol



Running NAPA batch file



NAPA-CAESES batch file v1 - Copy - Notepad

File Edit Format View Help

```
:: Copying INPUT files to the directory where NAPA reads them
copy "%CD%\Hull.iges" "C:\napa\pr\HROPAX_FC\Hull.iges"
copy "%CD%\variables00.txt" "C:\napa\pr\HROPAX_FC\variables00.txt"
```

COPYING INPUT FROM CAESES DIRECTORY TO NAPA DIRECTORY

```
::-----
:: THE BELOW SCRIPT CAN BE FOUND IN THE NAPA MANUAL
::-----
@echo off
setlocal

:: Please enter your details here
set USER=ADMI
set PROJECT=C:\NAPA\pr\hlopax_fc.db64
set MACRO=01_EXECUTE

:: General setup
set INSTALLATION_FOLDER=c:\napa\
set PATH=C:\Program Files\Hummingbird\Connectivity\14.00\Exceed

:: NAPA specific configuration
set NAPADB=c:\napa\20172\database\napadb.db
set SYSDB=C:\NAPA\pr\sysdb.db
set NAPALIC=C:\NAPA\pr\napalic.txt
set NAPIOF=C:\NAPA\pr\IOF_X64.dat
set NAPADIR=C:\NAPA\pr\

c:\napa\20172\bin64\NapaRunMacro.exe -u %USER% -f %NAPADIR%
                                     -l %NAPALIC% -n %NAPADB%
                                     -s %SYSDB% -i %NAPIOF%
                                     -p %PROJECT% -m %MACRO%

::-----
:: END OF NAPA MANUAL SCRIPT
::-----
```

RUNNING NAPA*

***script can be found in NAPA manual**

Batch file

Needs to be adjusted to working environment

```
:: Copying the OUTPUT files in the directory where CAESES saves them
copy "C:\napa\pr\HROPAX_FC\output.txt" "%CD%\output.txt"
copy "C:\napa\pr\HROPAX_FC\damstabres.txt" "%CD%\damstabres.txt"
```

COPYING OUTPUT FROM NAPA DIRECTORY TO CAESES DIRECTORY



CAESES as a platform (and “operating system”)



User (internal)



User (internal)



User (external)



Web user



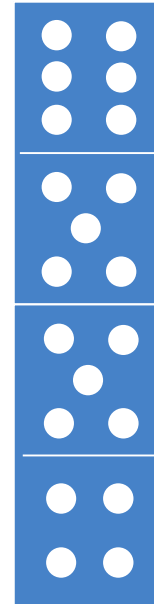
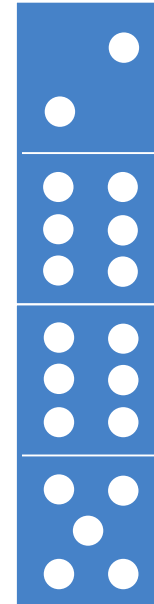
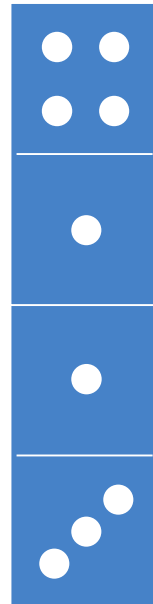
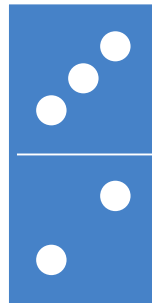
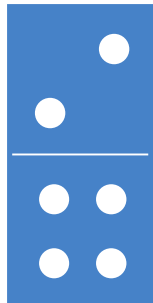
Web user



Expert user



Specialist



FS team



CAESES 5.0



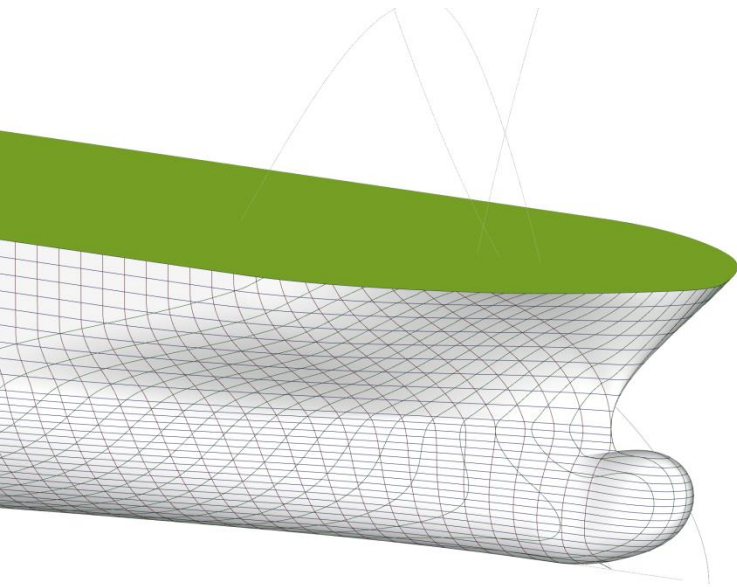
CAESES 5.0

- Parallelized
 - CAESES 5.0 exploits all cores of multi-core machines (while 4.x uses only one core)
 - Speeds up project loading and model update (depending on the project, up to a linear scaling with regards to number of cores)
- New rendering engine
 - Handling of larger objects
 - Better user experience
 - Nicer pictures
- Base for appification



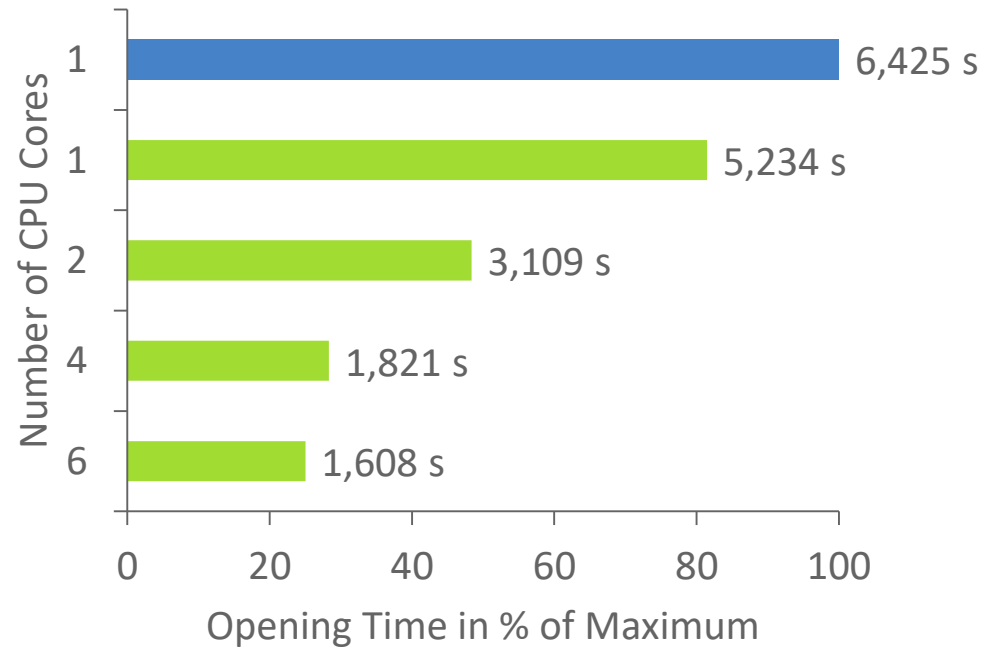
Speed up in CAESES 5.0

- Parametric CAESES model of a container vessel
- Good scaling on multiple CPUs



Up to 4 x faster

Using 6 cores instead of one

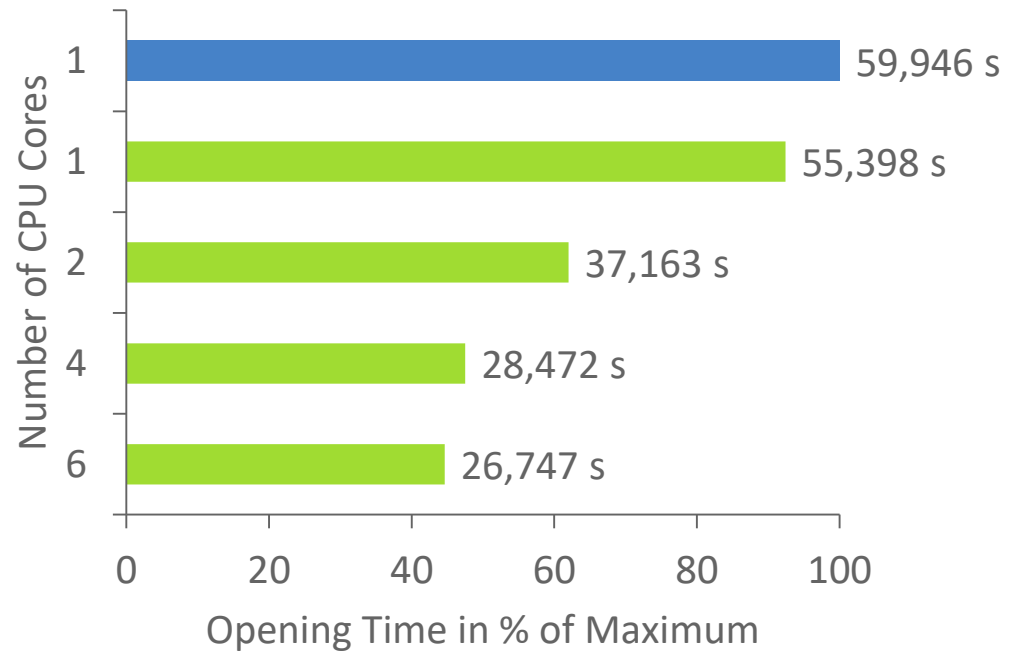


Speed up in CAESES 5.0

- Turbine example modeled in CAESES
- Scaling depends on hierarchical model



Opening time reduced by more than 30 seconds
Using 6 cores instead of one

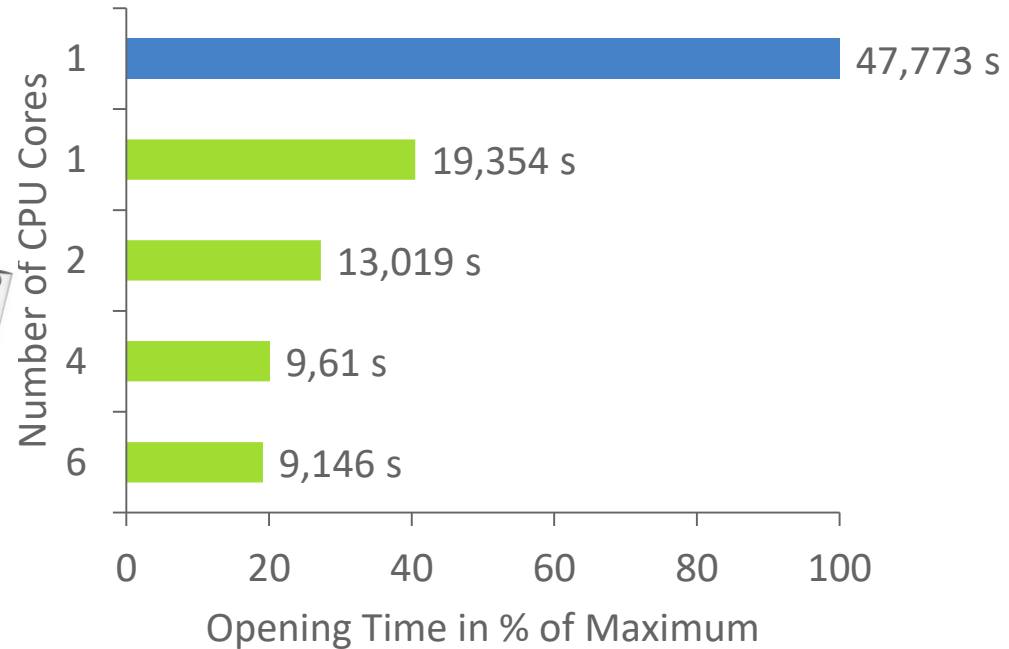
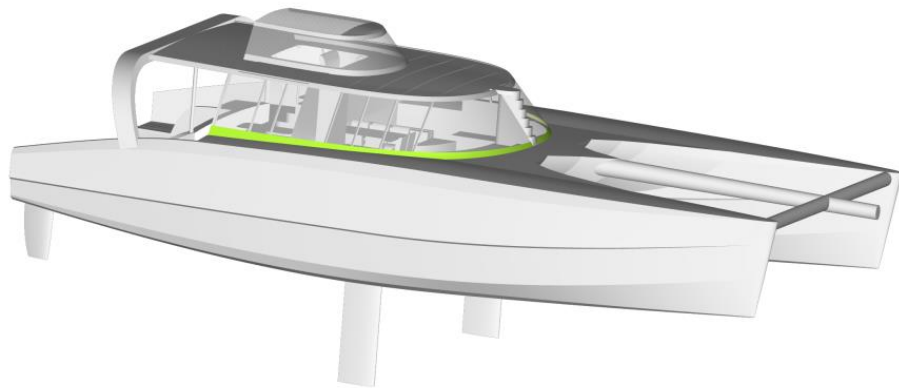


Speed up in CAESES 5.0

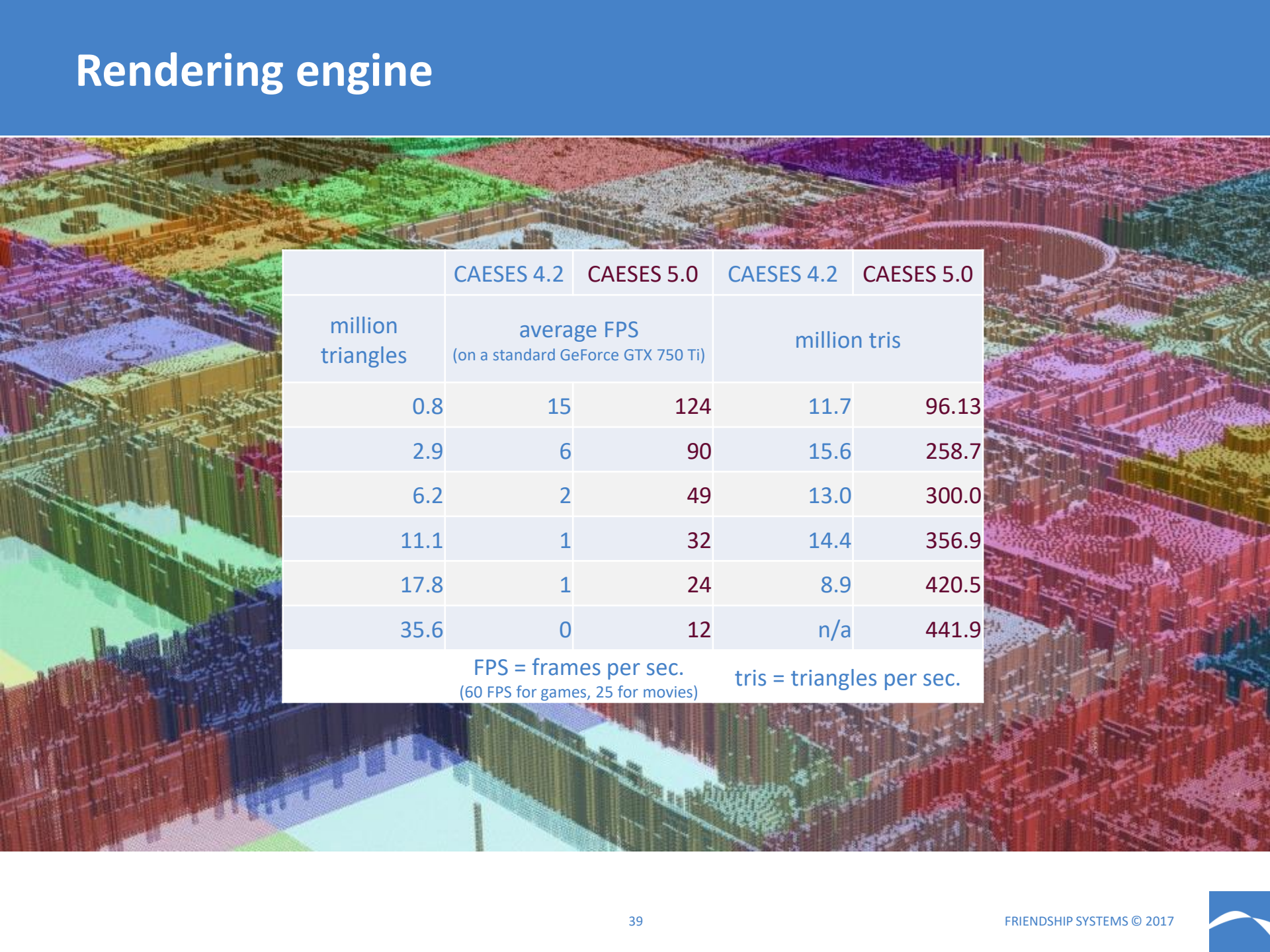
- Complex model of a catamaran
- Created in 4.2 runs flawless in CAESES 5.0

Better performance already in serial mode

Opening time reduced by 60%



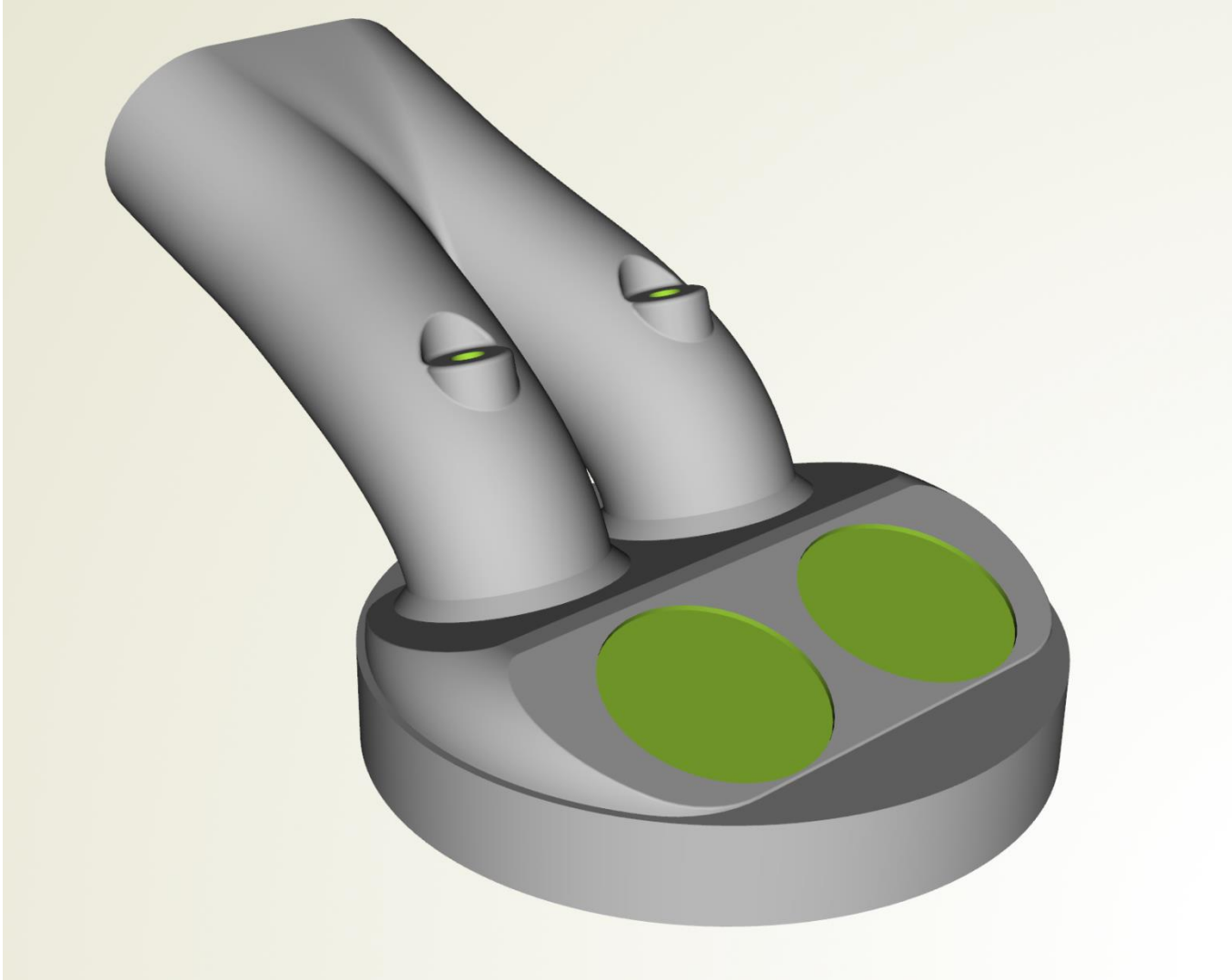
Rendering engine



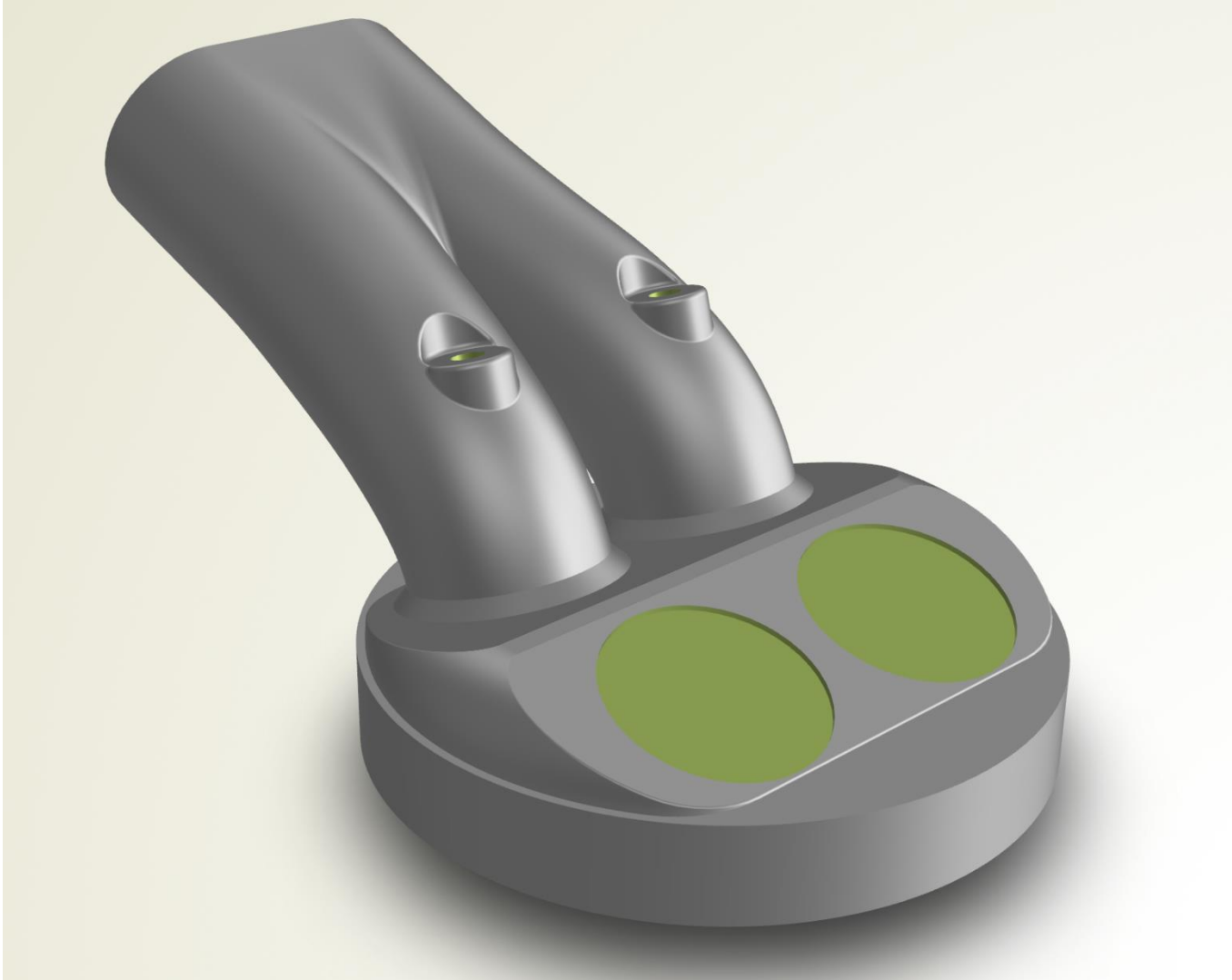
| | CAESES 4.2 | | CAESES 5.0 | |
|--|---|-----|--------------|---------------------------|
| million triangles | average FPS
(on a standard GeForce GTX 750 Ti) | | million tris | |
| 0.8 | 15 | 124 | 11.7 | 96.13 |
| 2.9 | 6 | 90 | 15.6 | 258.7 |
| 6.2 | 2 | 49 | 13.0 | 300.0 |
| 11.1 | 1 | 32 | 14.4 | 356.9 |
| 17.8 | 1 | 24 | 8.9 | 420.5 |
| 35.6 | 0 | 12 | n/a | 441.9 |
| FPS = frames per sec.
(60 FPS for games, 25 for movies) | | | | tris = triangles per sec. |



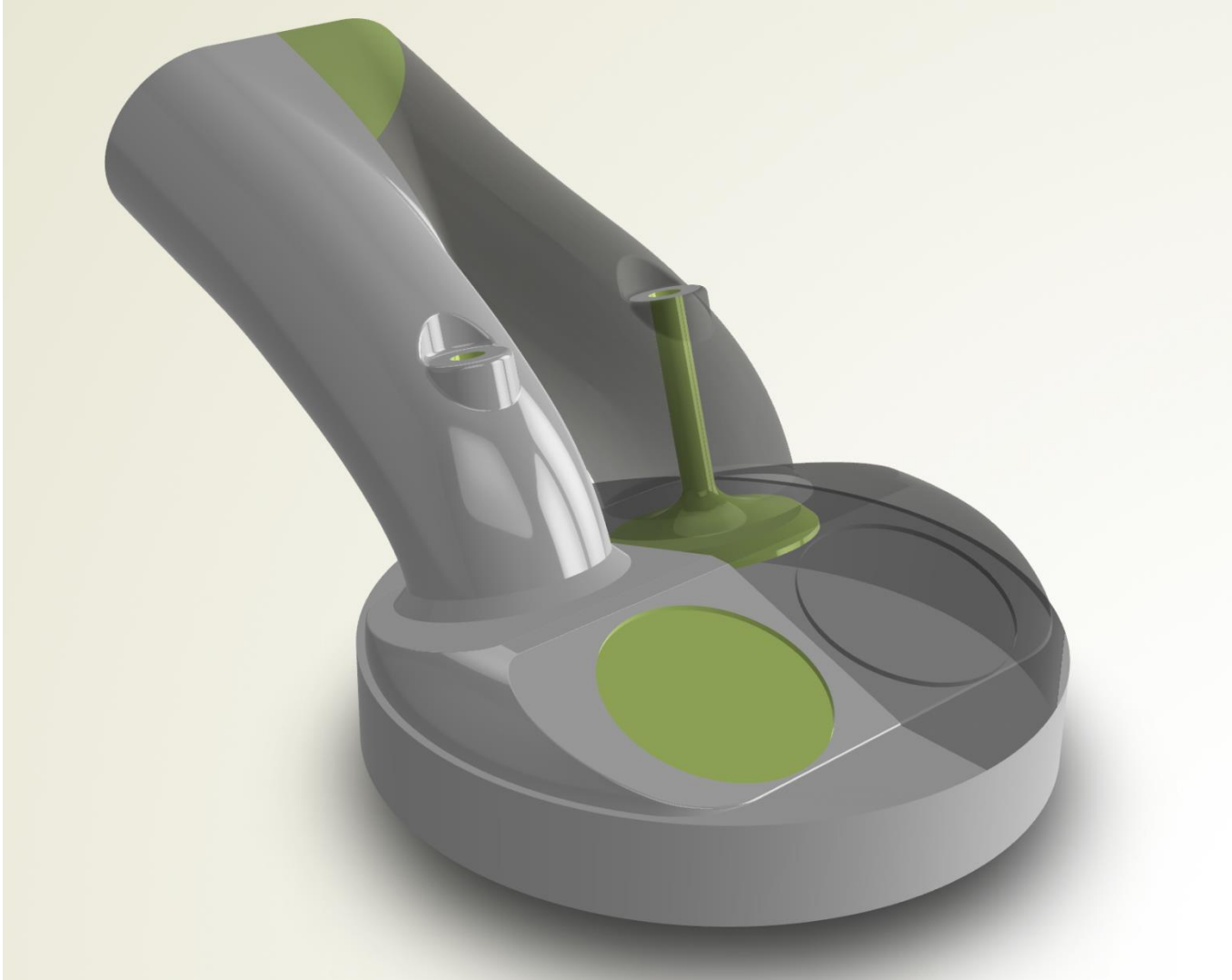
Rendering engine 4.x



Rendering engine 5.0



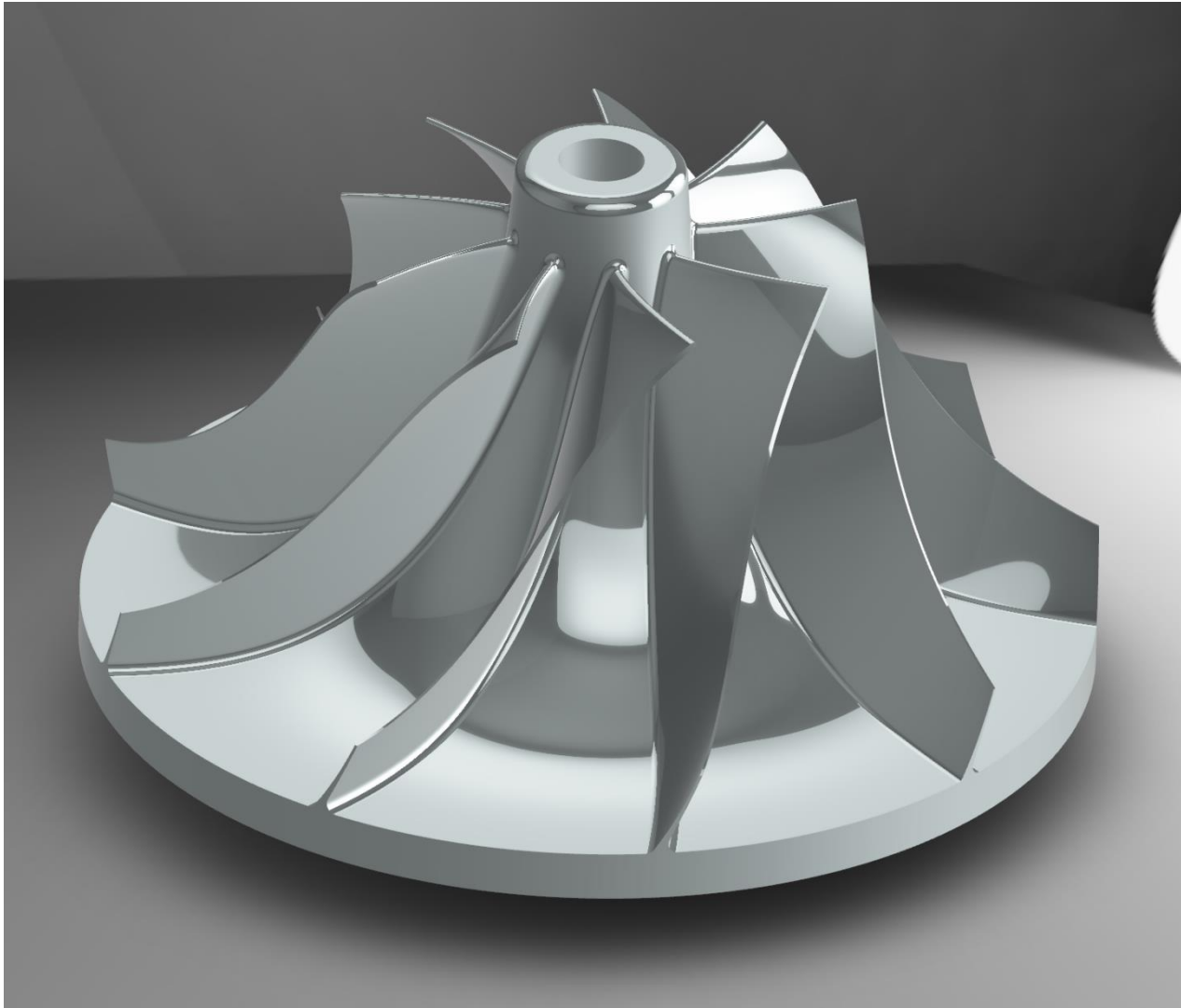
Rendering engine 5.0



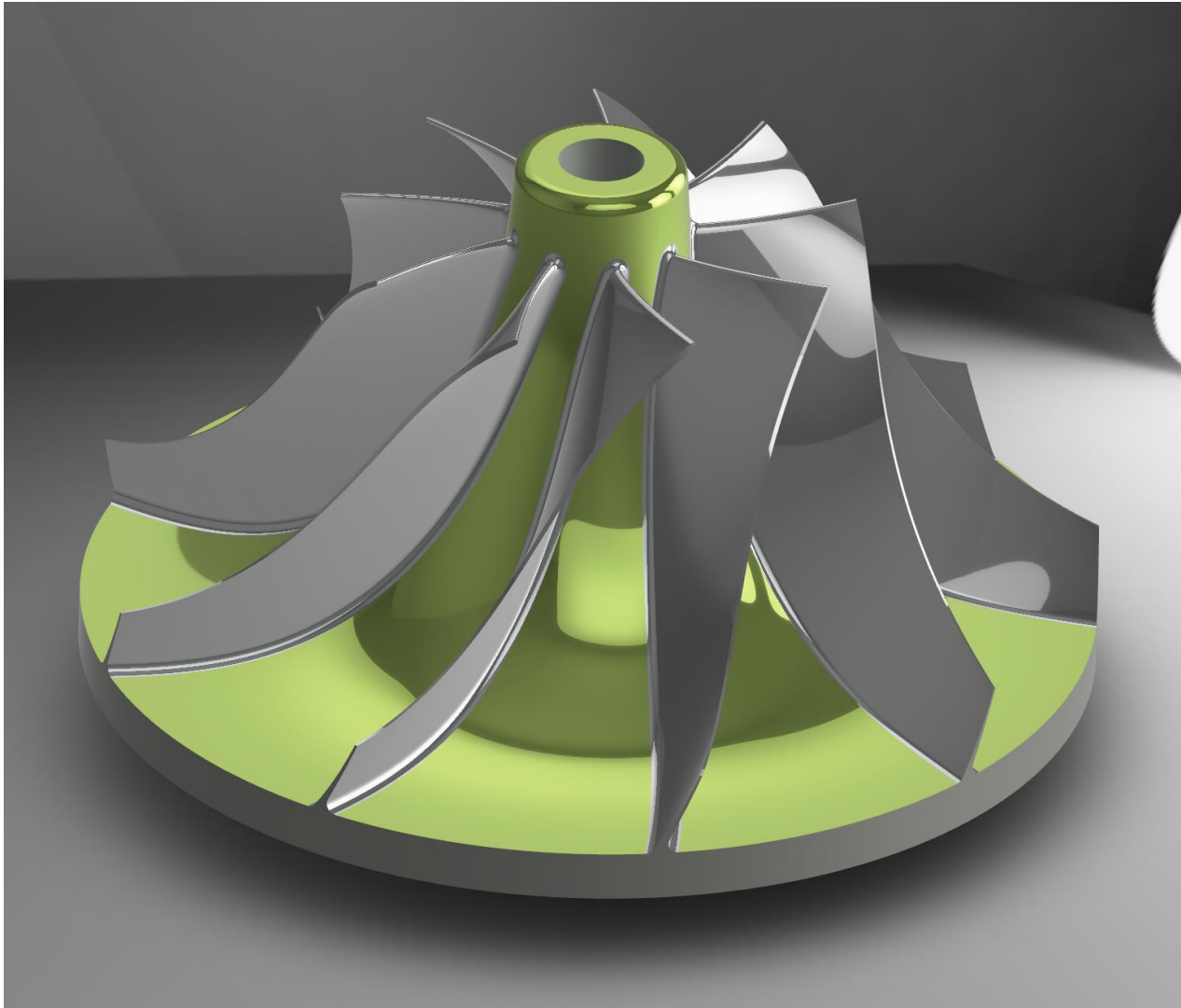
Rendering engine 4.x



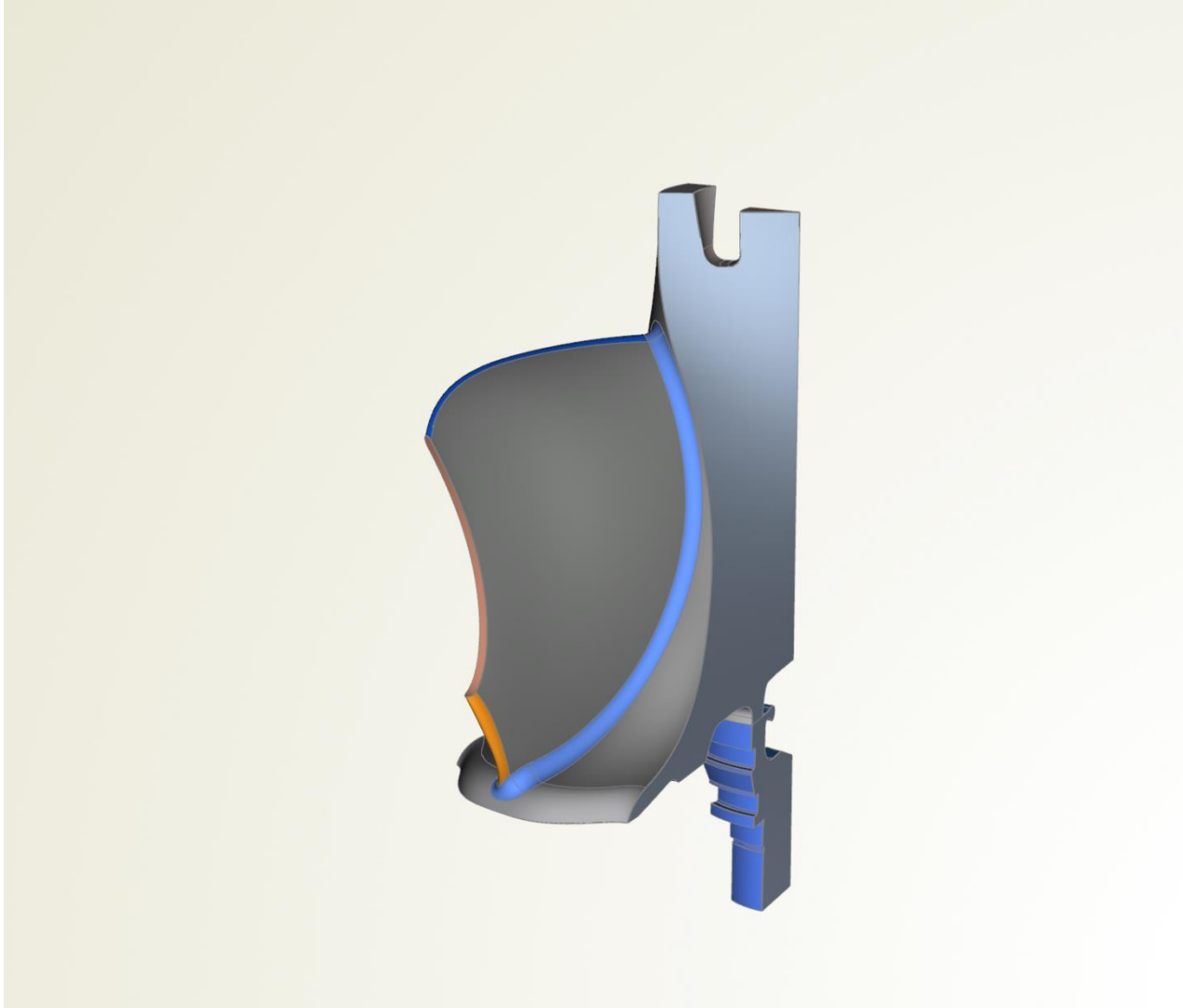
Rendering engine 5.0



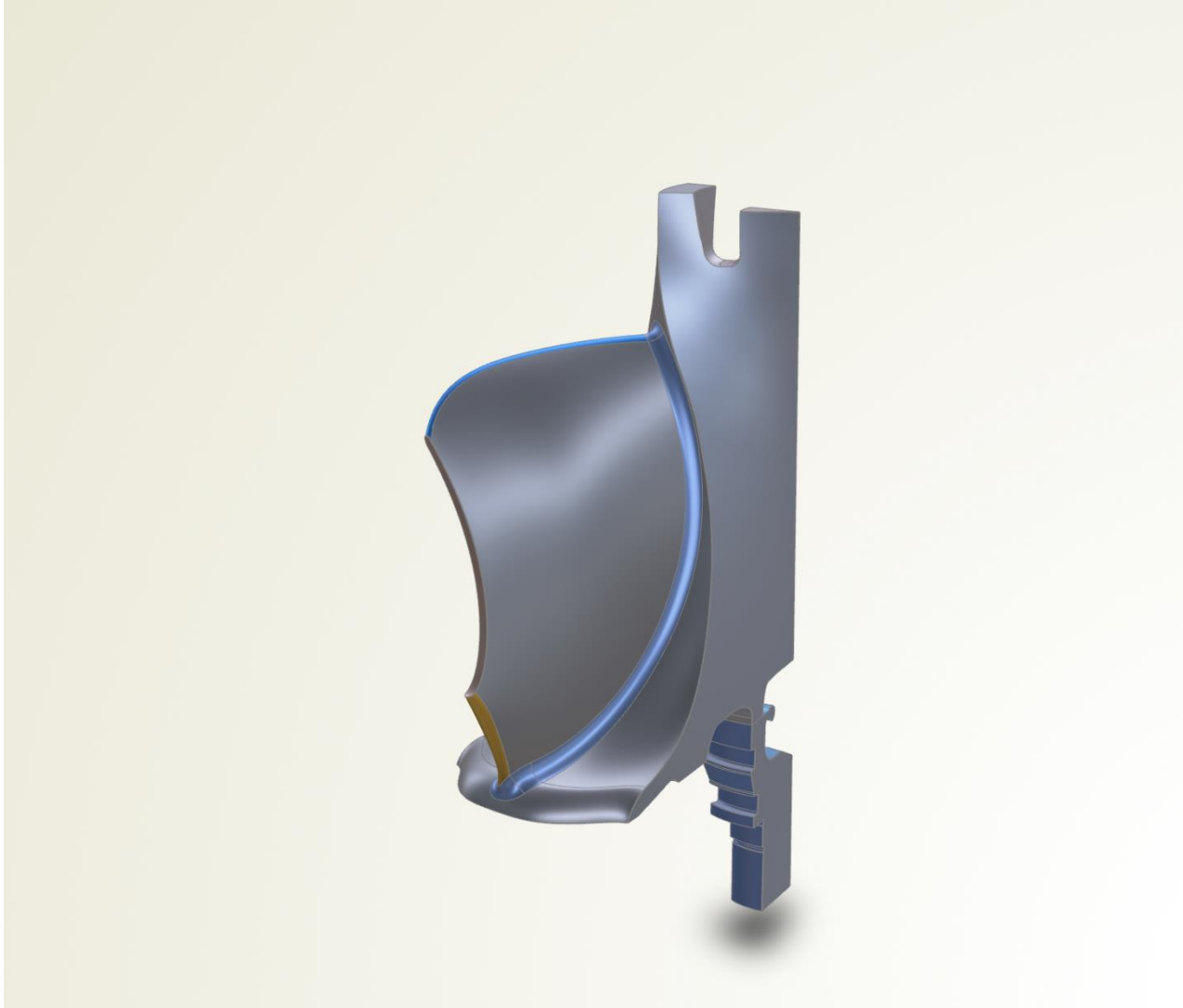
Rendering engine 5.0



Rendering engine 4.x



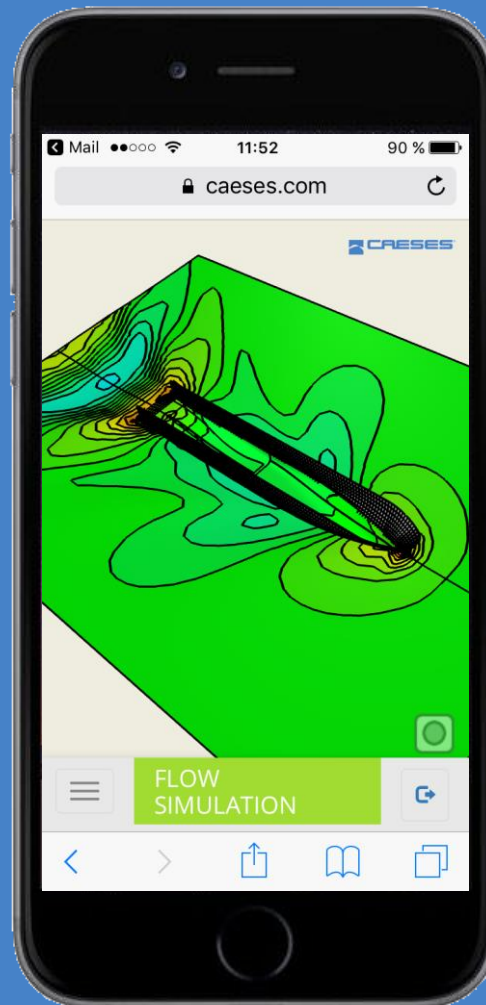
Rendering engine 5.0



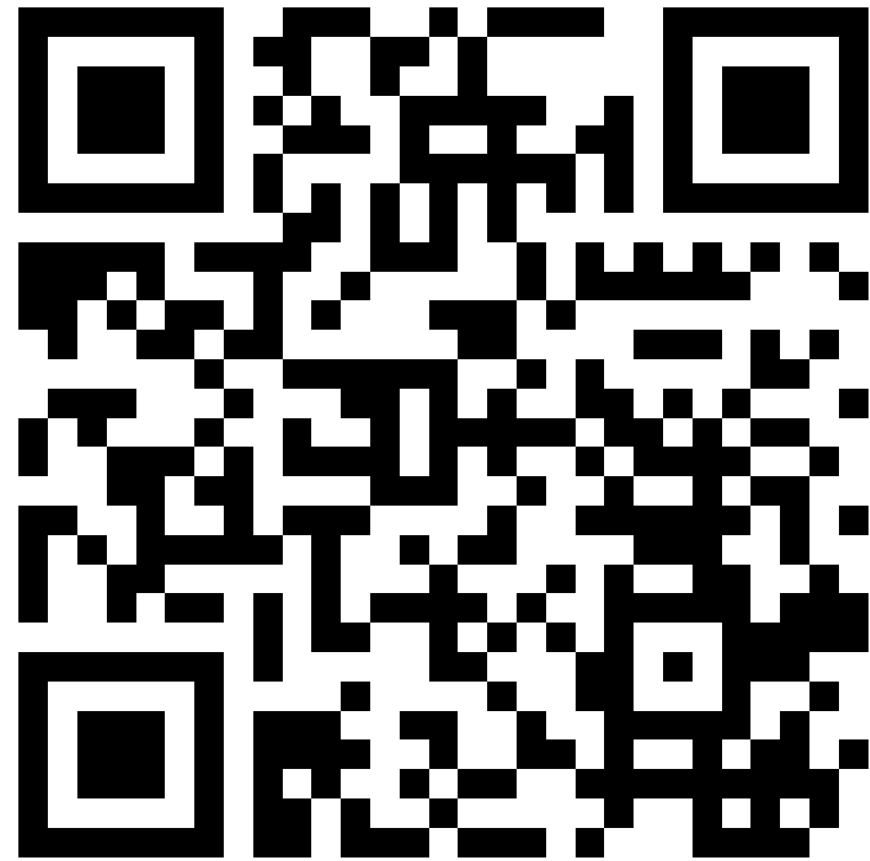
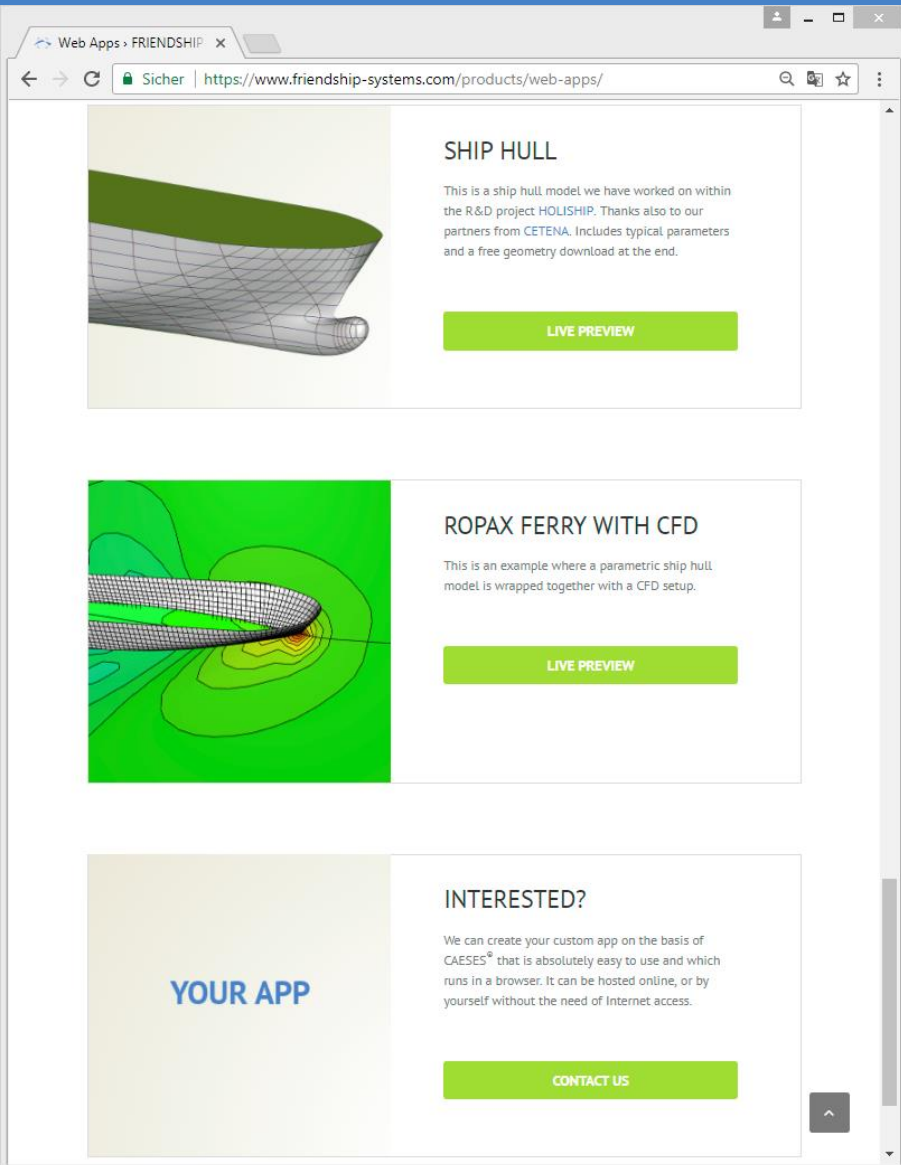
Rendering engine 5.0



Appification and WebApps



Appification

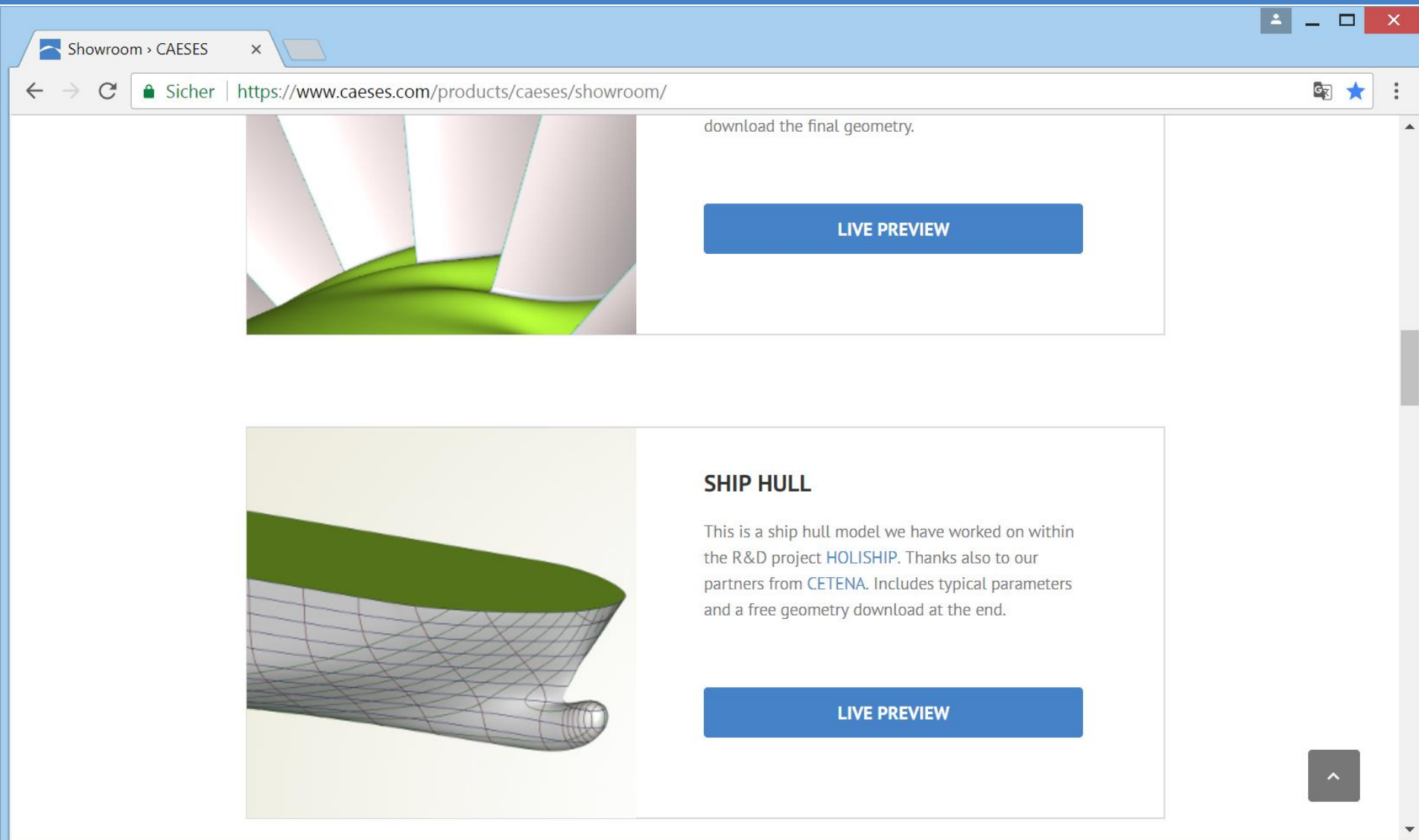


Website

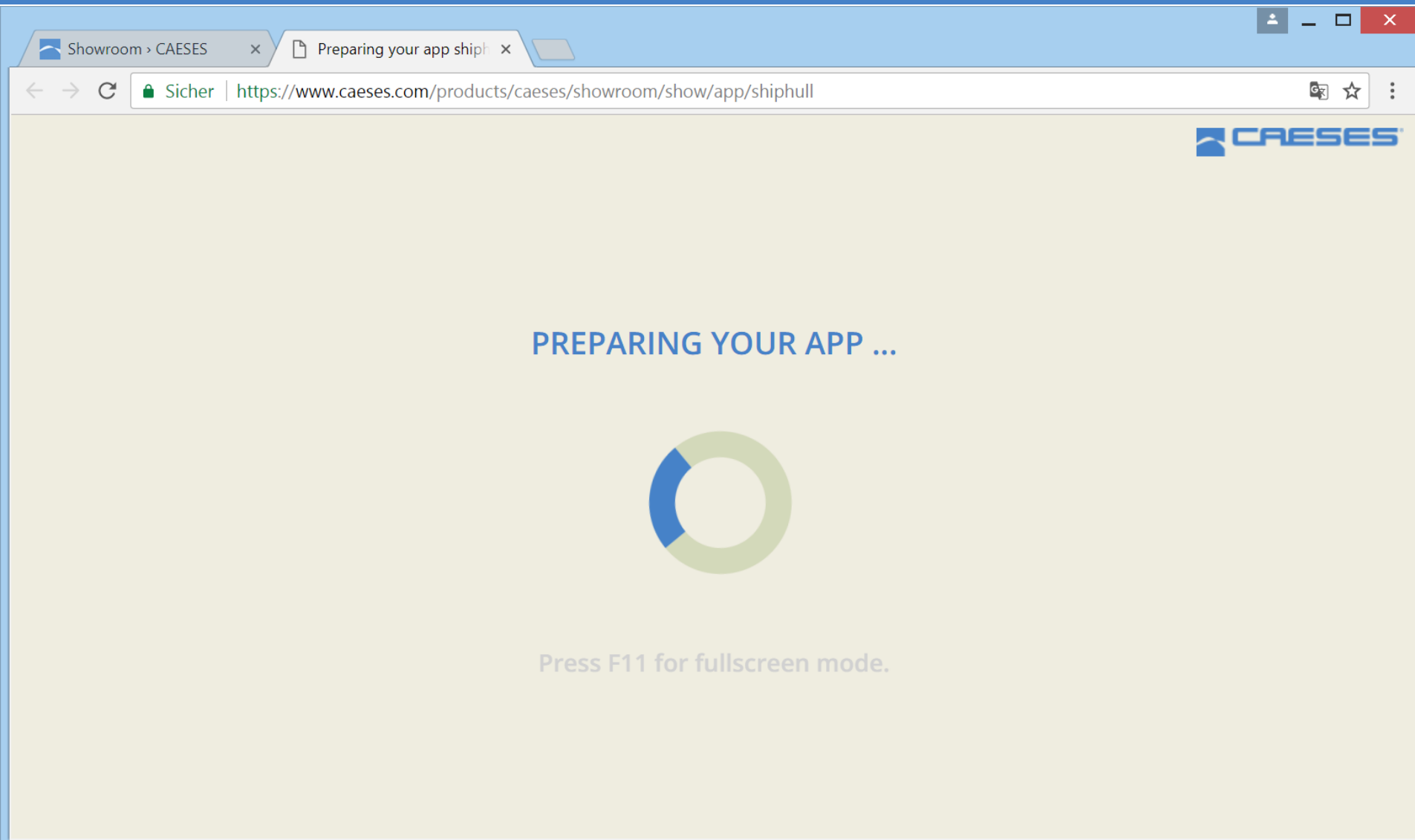
<https://www.friendship-systems.com/products/web-apps>



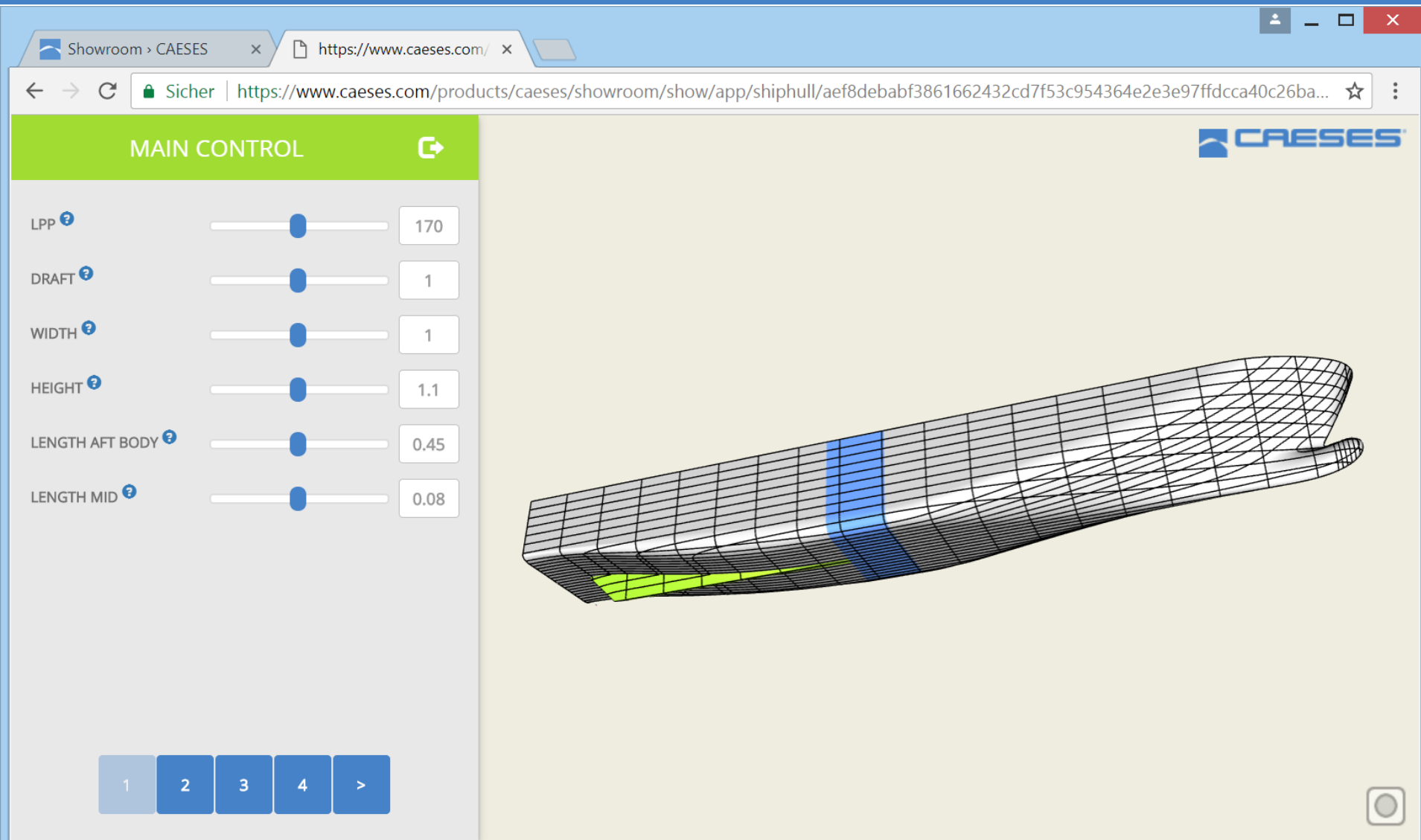
Example WebApp



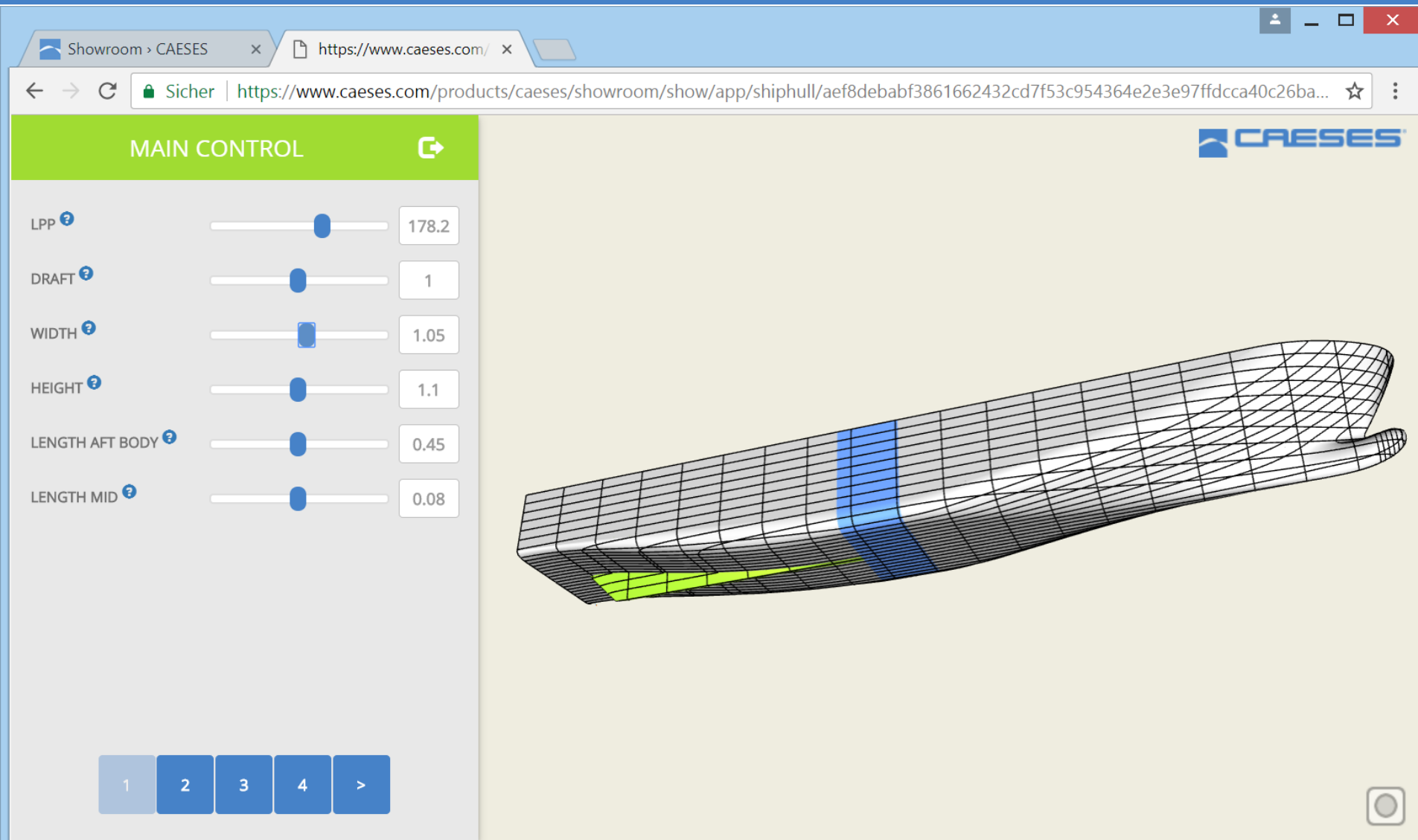
Example WebApp



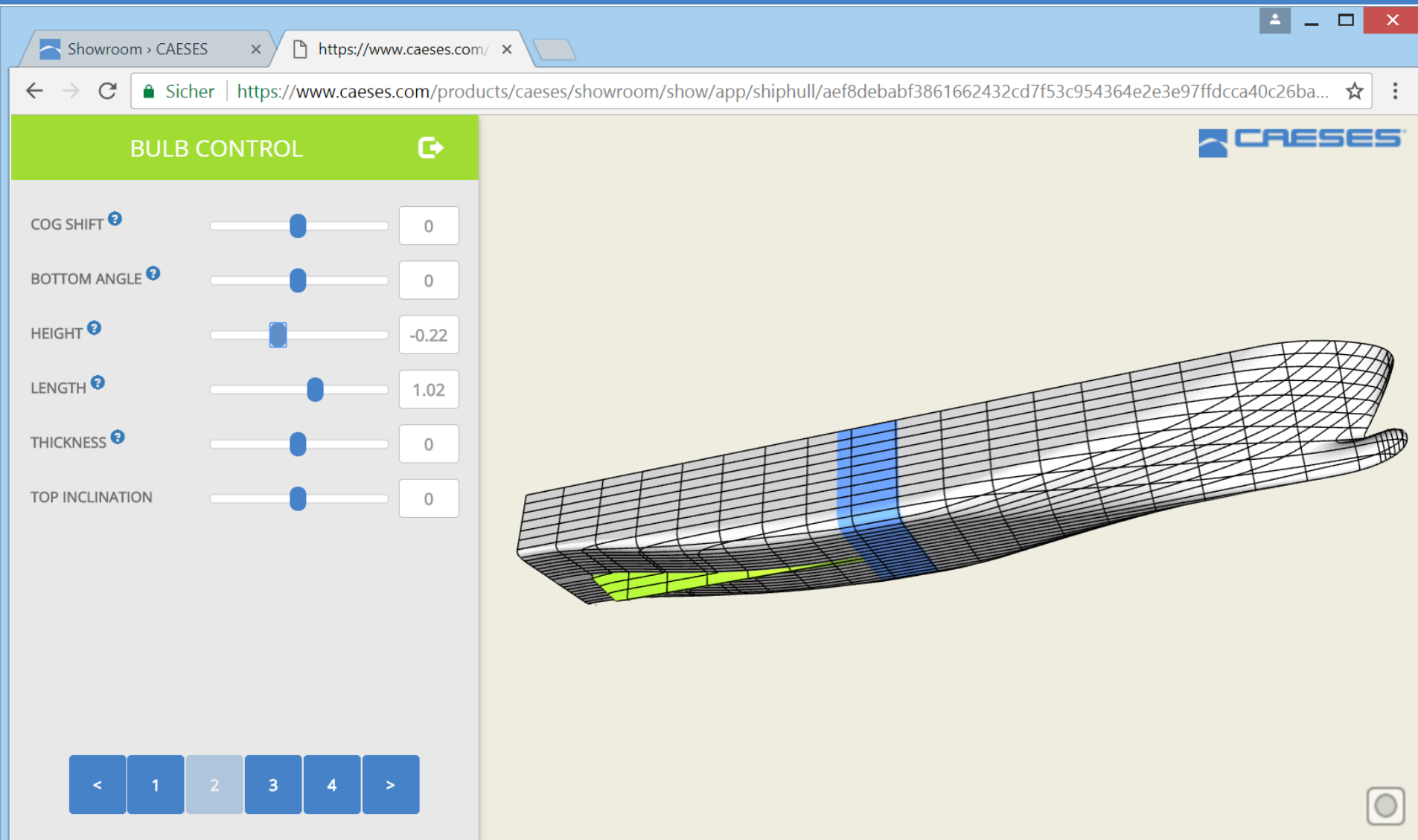
Example WebApp



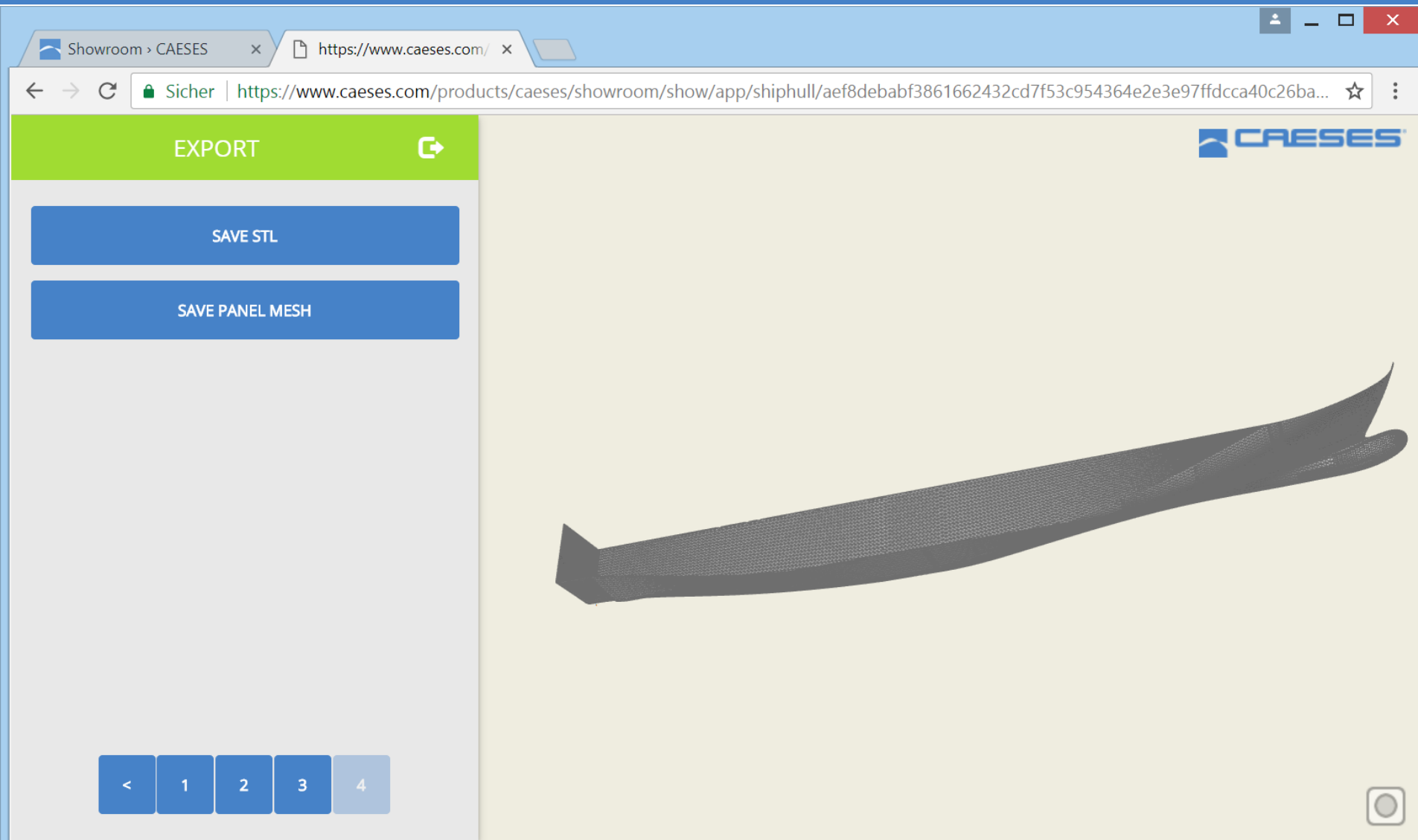
Example WebApp



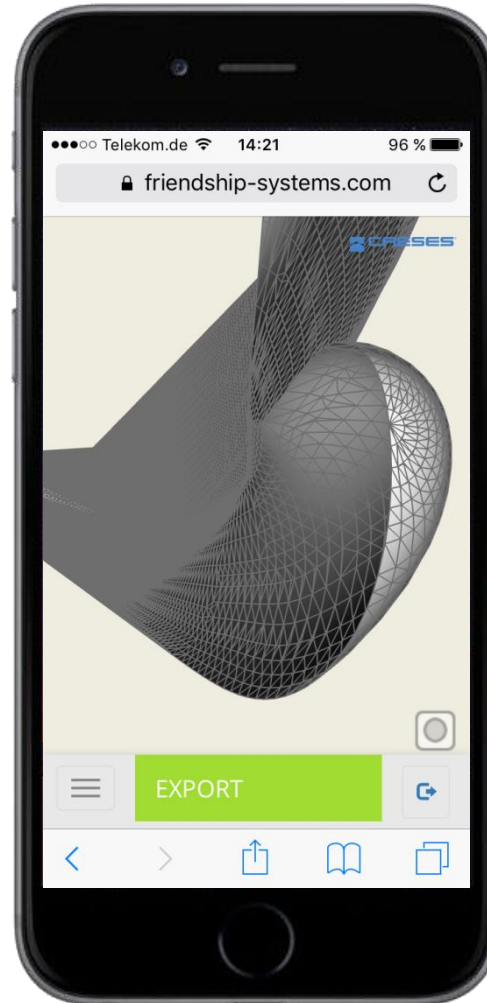
Example WebApp



Example WebApp



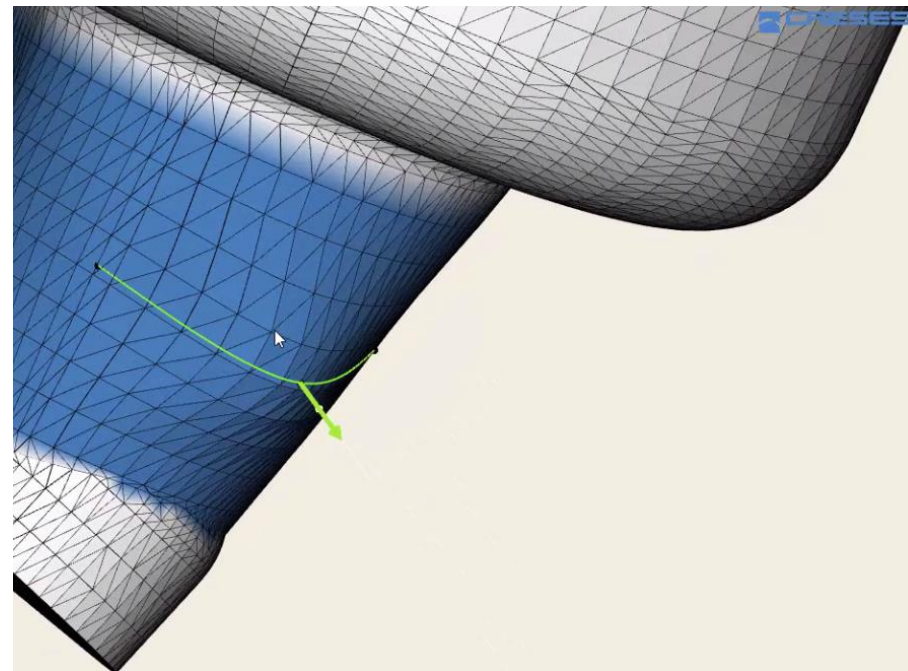
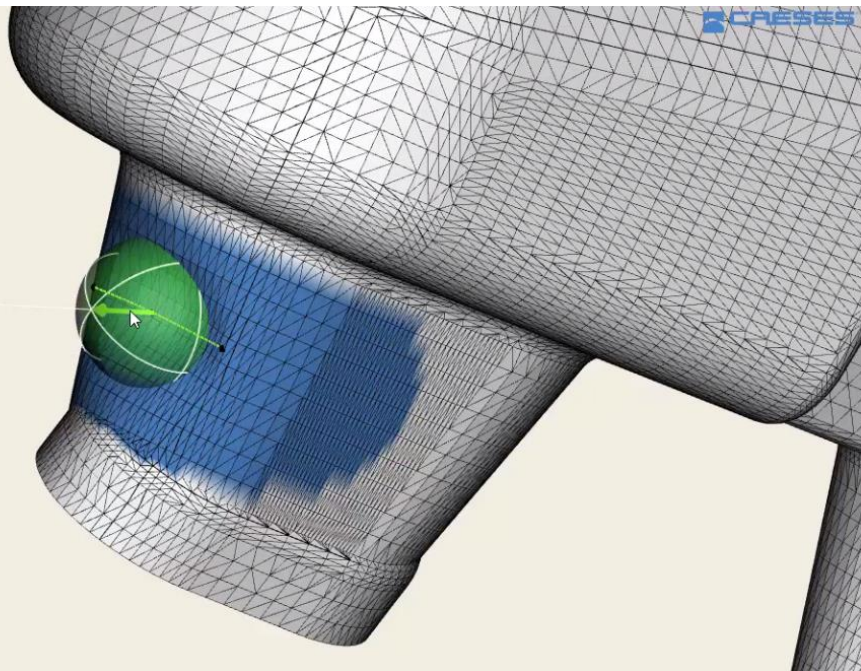
Example WebApp



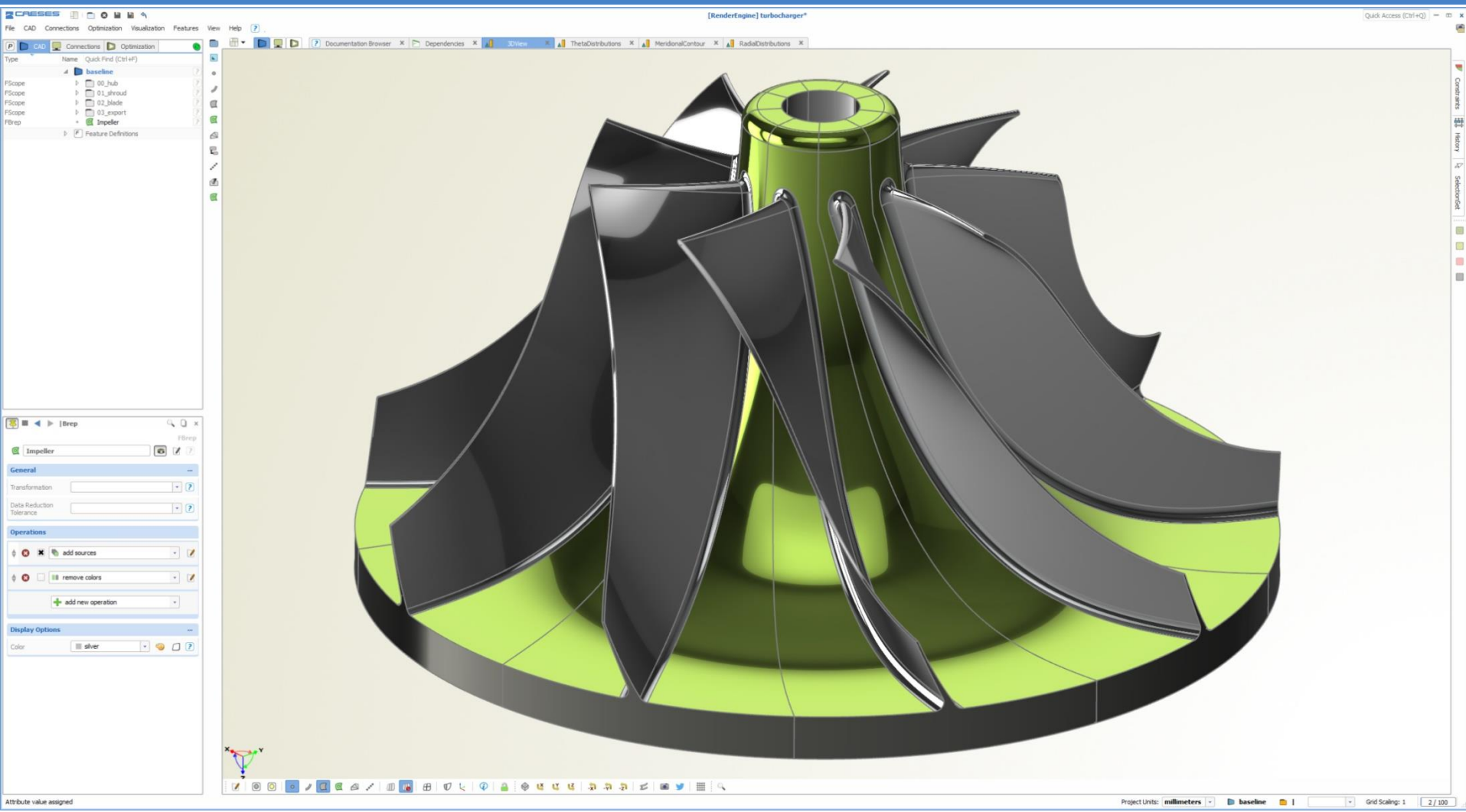
Sneak preview: Interactive shape variation



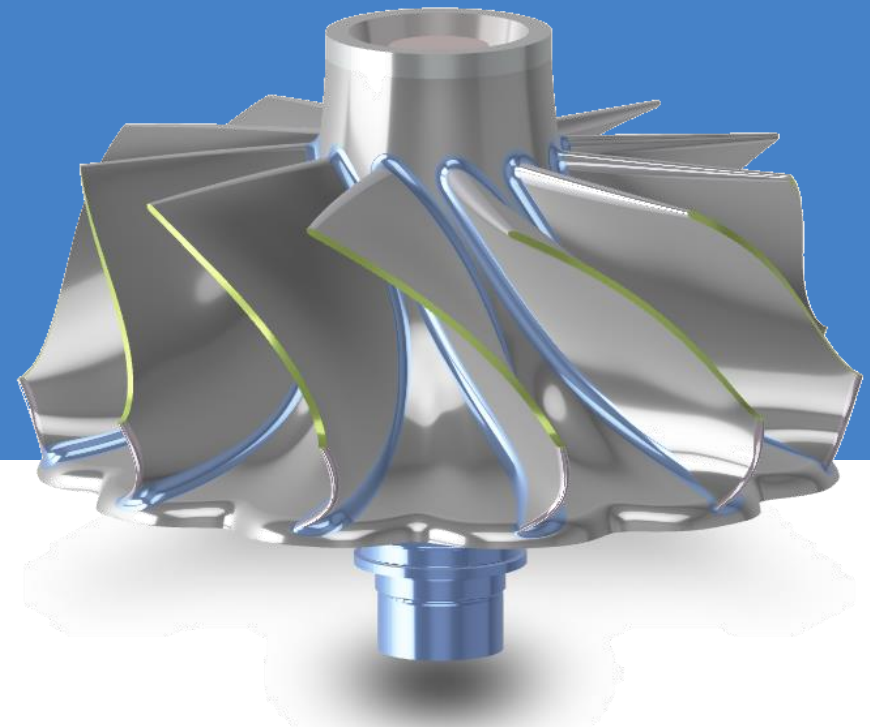
Sneak preview: Interactive shape variation



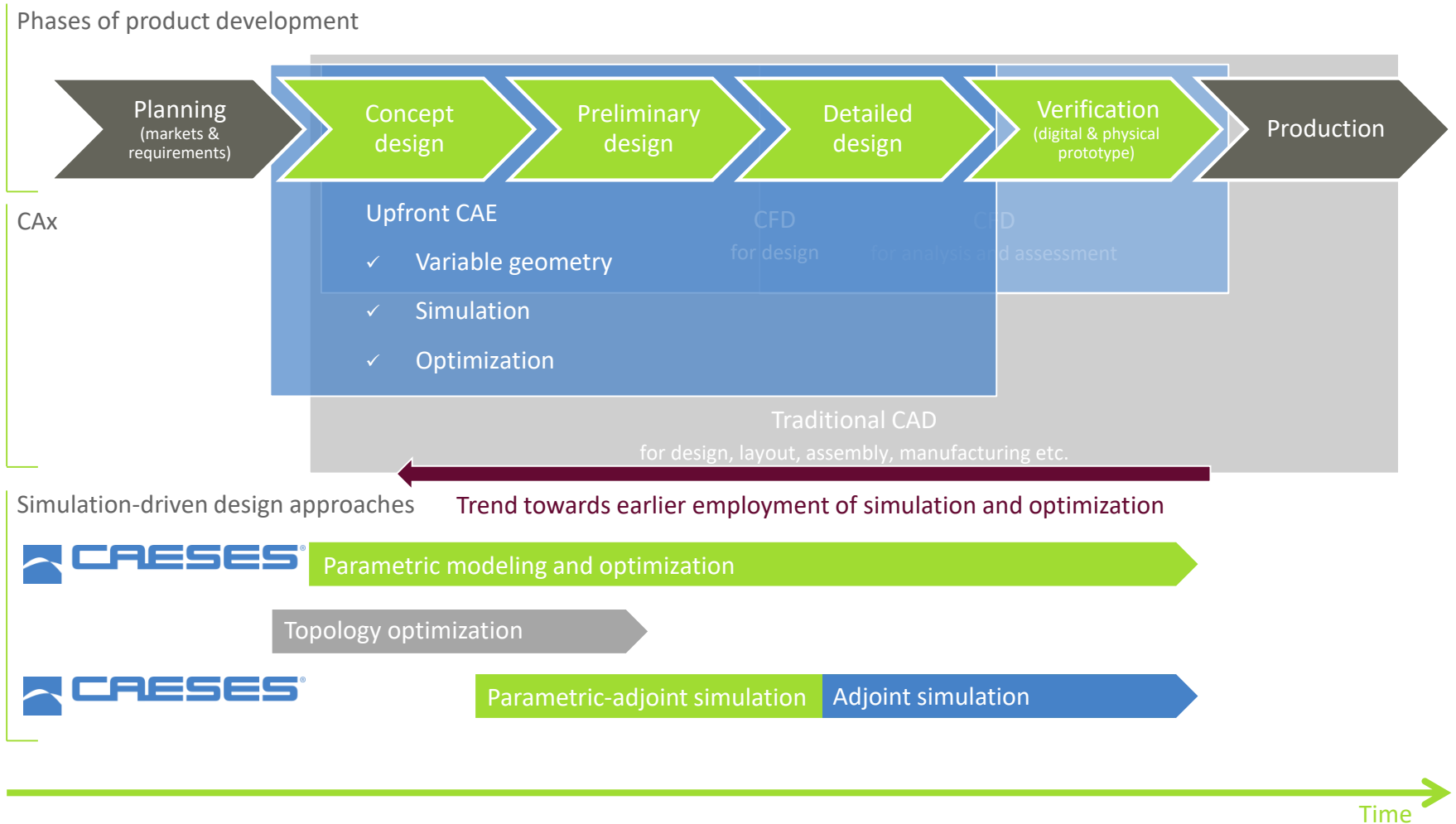
Thank you very much



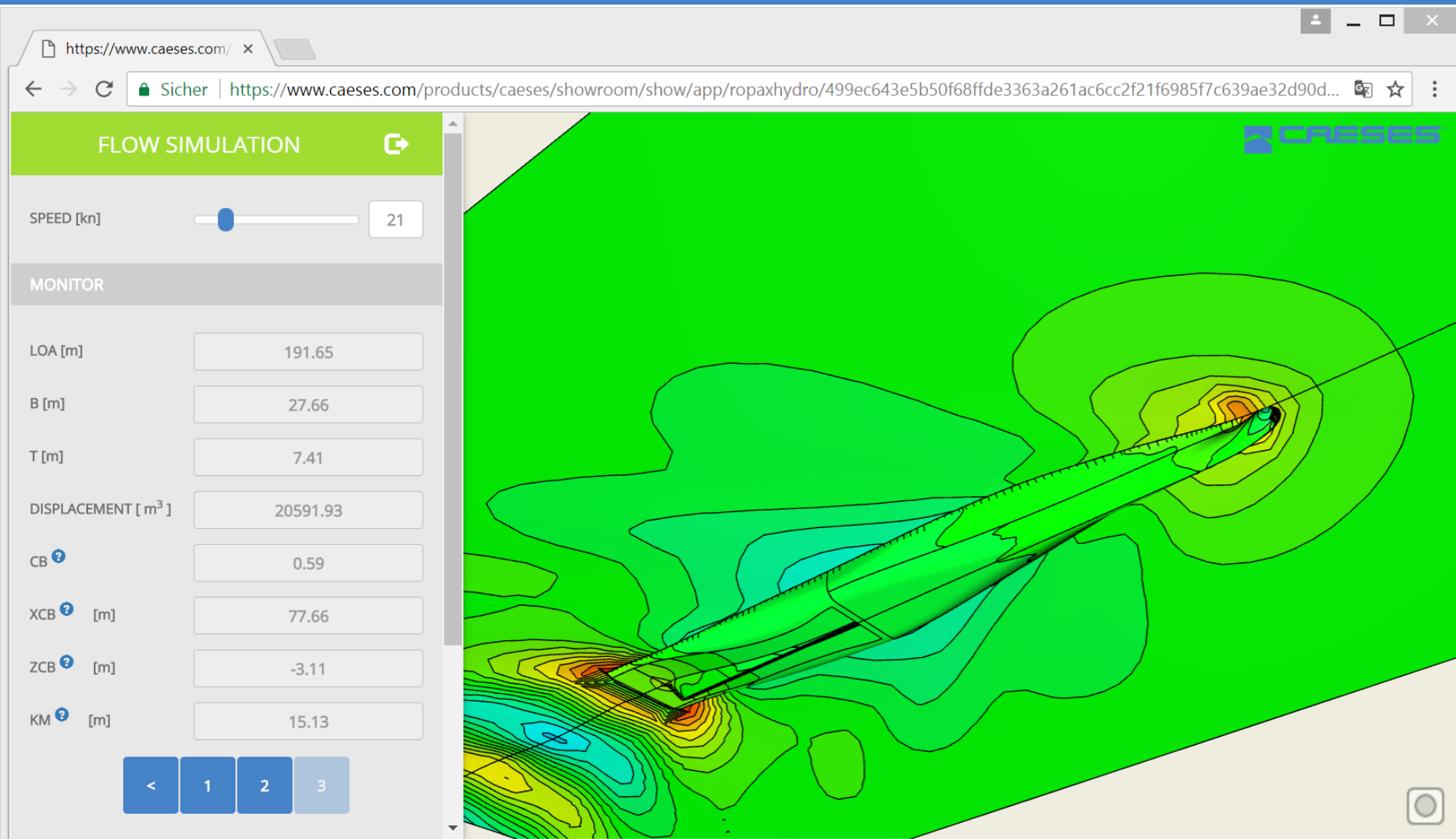
www.CAESES.com



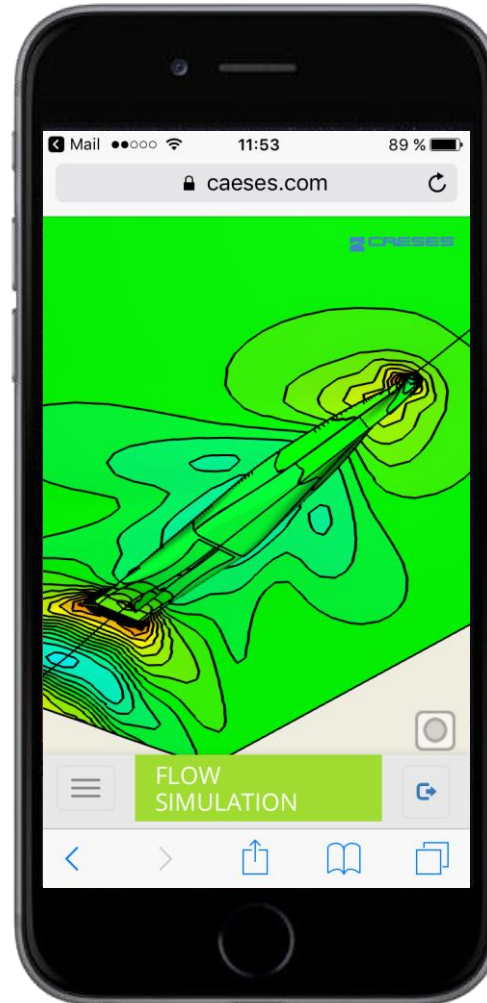
Simulation-driven design with CAESES



Example webApp



Example webApp



Encapsulate functionality and make them accessible

about the Wageningen B-Series propeller.



THIS IS HOW IT WORKS

- ✓ Enter your information about the ship vessel and the propulsion system
- ⚙ We do the calculation for you to find the right dimensions and propeller shape
- ✓ Check the visualization of the propeller
- ✓ Download a demo STL of the propeller for a check on your computer
- ⬇ Download the final STEP/STL file of the propeller



Documentation and support

- YouTube
- Blog
- Forum
- Documentation browser
- Helpdesk

The screenshot displays the CAESSES Helpdesk interface. The top navigation bar includes links for Dashboard, Tickets, Social, Solutions, Forums, Customers, Reports, and Admin. The main content area shows a ticket titled "The connection with AVL Fire" reported 13 days ago. The ticket description includes a greeting, a request for help with connecting CAESSES to AVL Fire, and a thank you. A public note from Mr. Carsten Fuetterer is also visible, mentioning template files and a batch script. The right sidebar contains a status box "Waiting on Customer", requester information, and ticket properties such as Priority (Low), Status (Waiting on Cust...), Source (Portal), Group (...), Agent (Mr. Carsten Fuetterer), Type (Question), My CAESSES Version (4.2.1), and Category (Software Connection).